

Markus Elsing

Tracking at the LHC (Part 6)

● **High Luminosity and Upgrade**



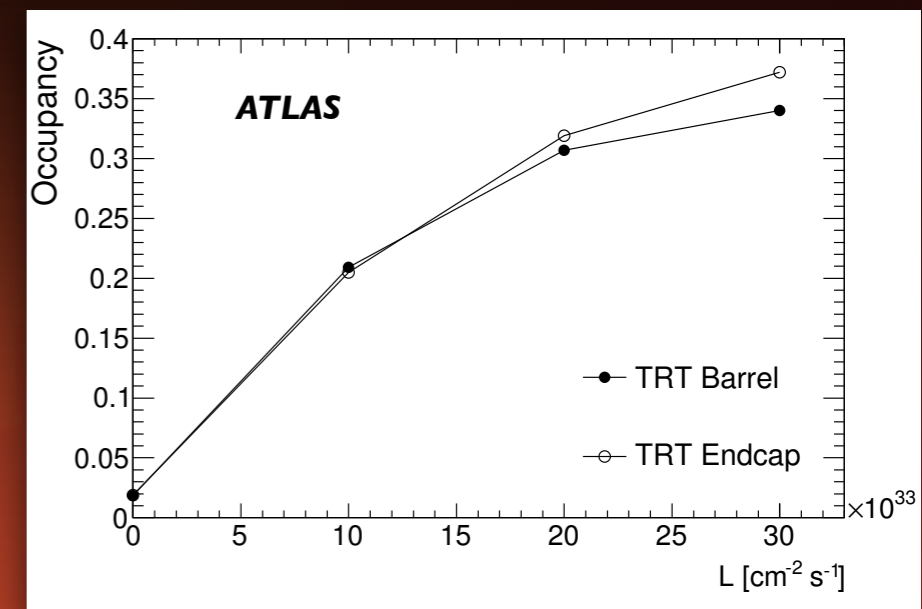
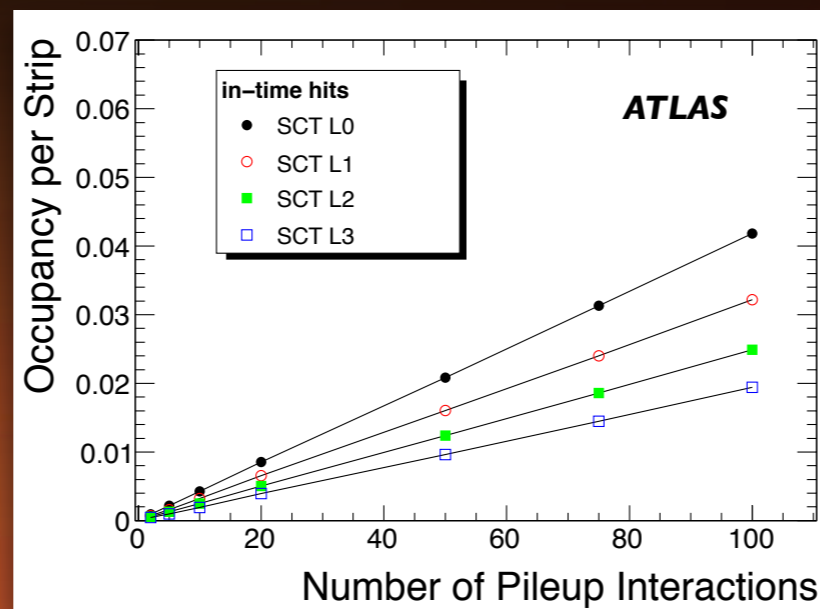
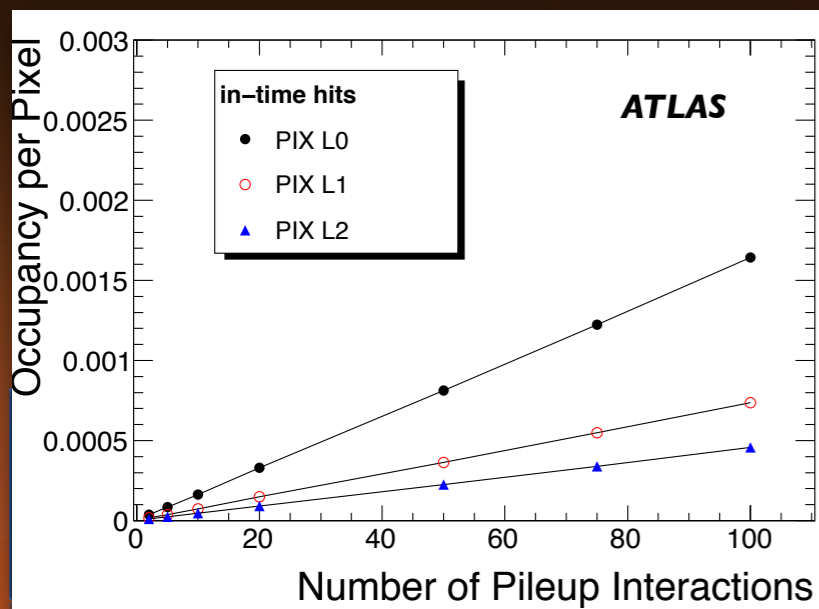
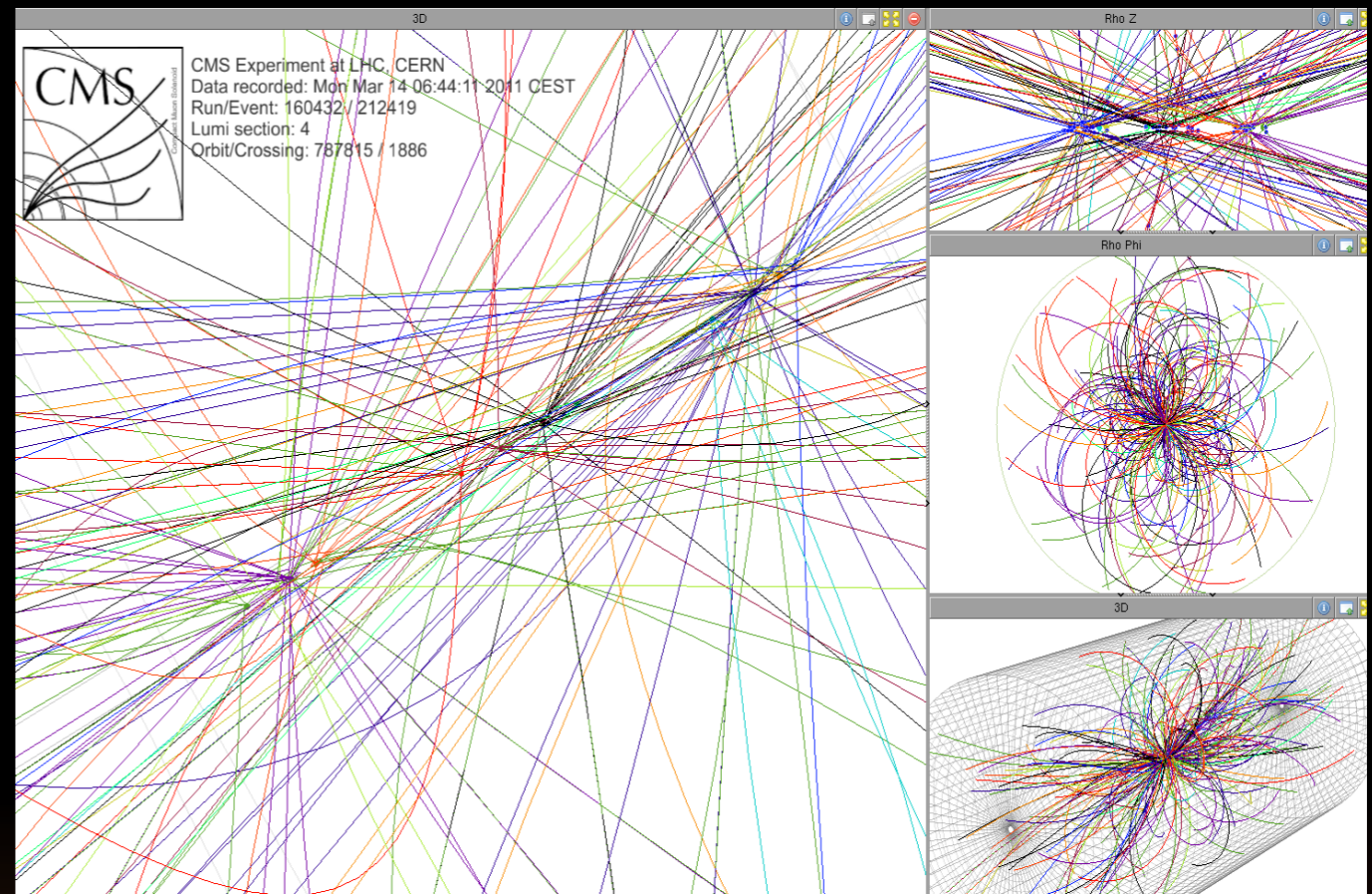
Outline of Part 6

- expected tracking performance with high pileup
- evolution of tracking settings
 - ➔ including CPU and memory/size issues
 - ➔ brief look at heavy ion data to study those
- discuss Phase-0 and Phase-1 upgrades for CMS+ATLAS
 - ➔ as well hardware track trigger concepts



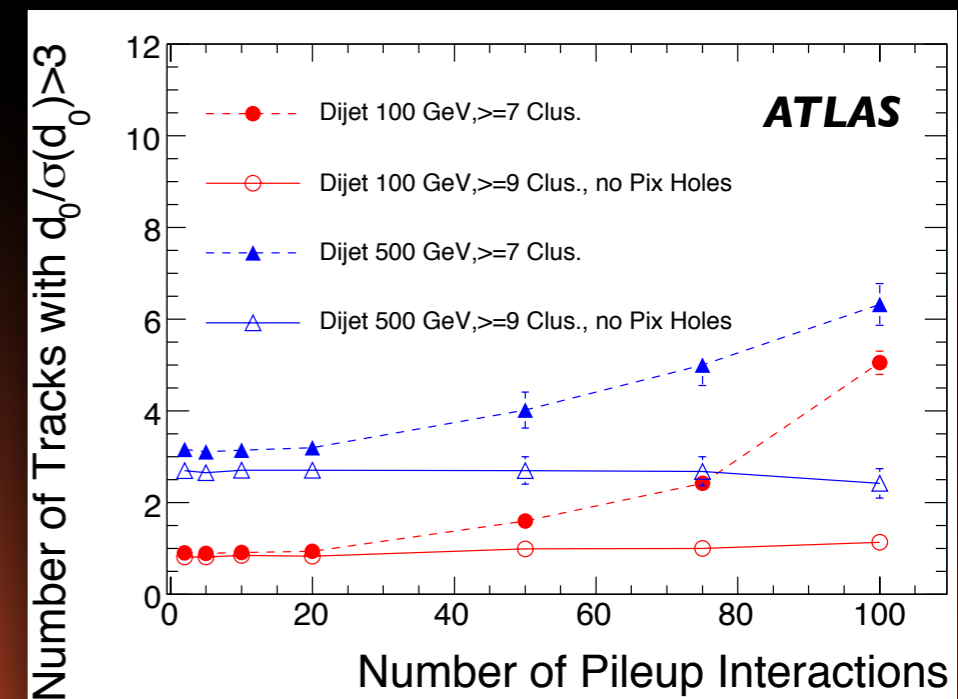
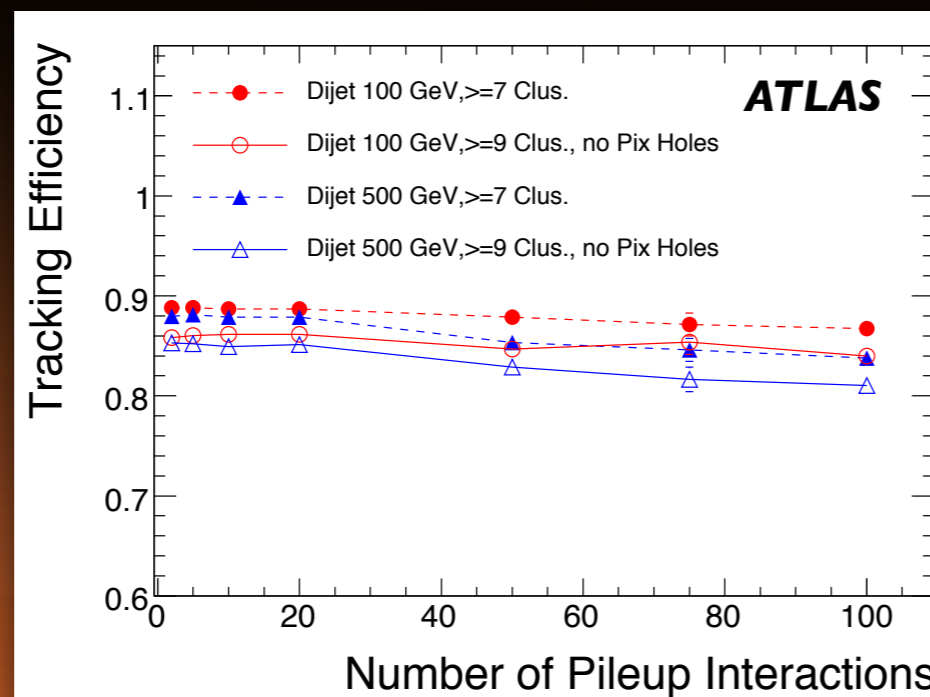
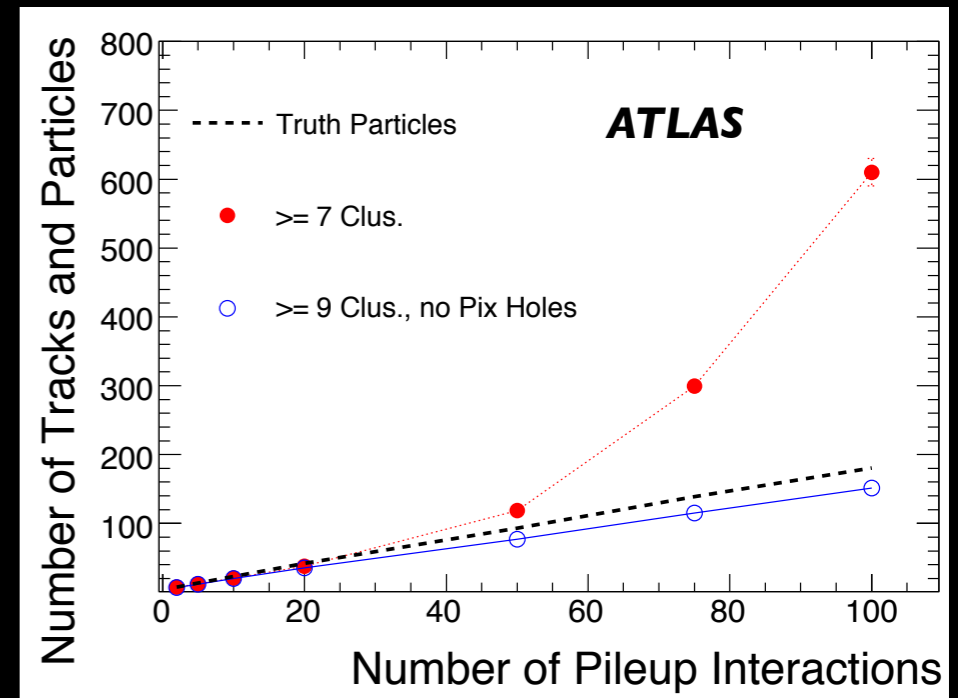
Tracking for High Occupancy - Pileup

- event pileup is a feature of the LHC
 - ➔ already sizable effects this year
 - ➔ ~23 events at design lumi
- detectors designed for $10^{34} \text{ cm}^{-2} \text{ s}^{-1}$
 - ➔ occupancies from pileup do not exceed hit density in jet cores !



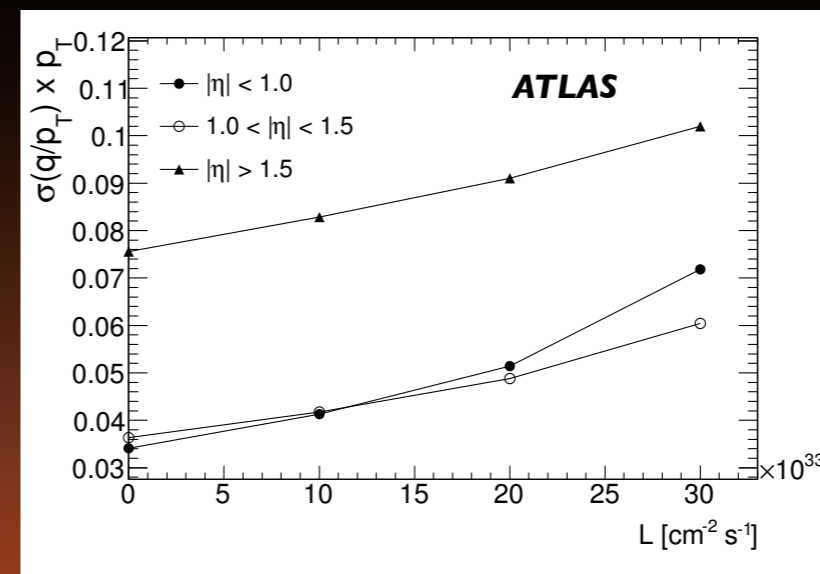
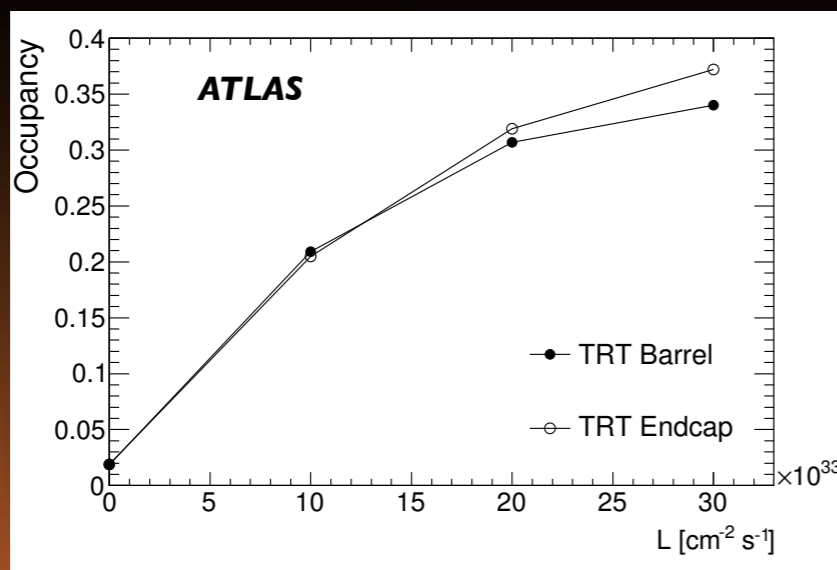
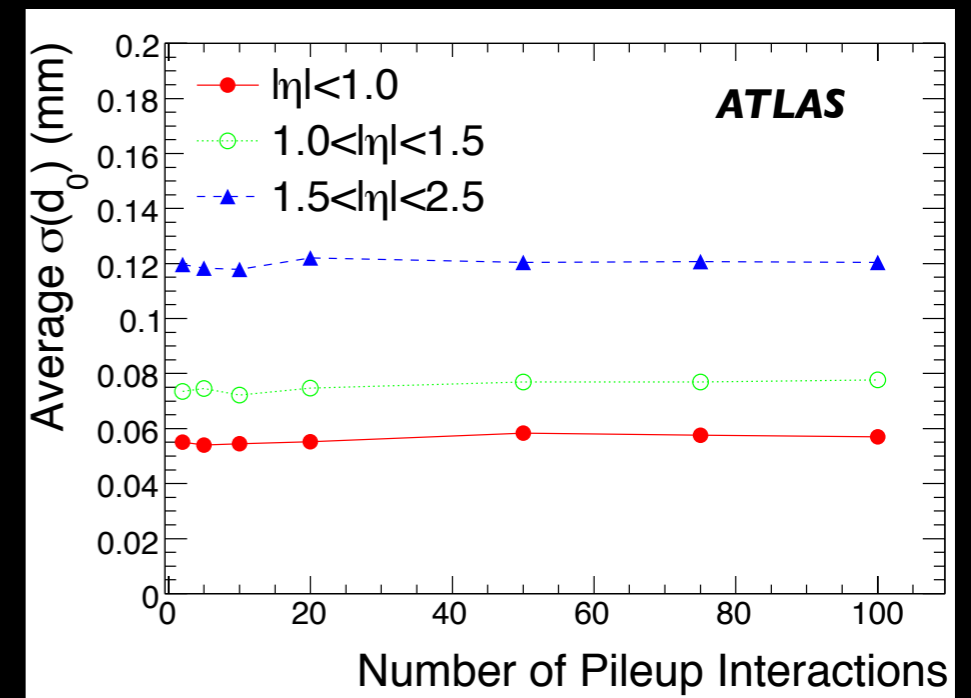
Tracking at High Luminosity (pp)

- tracking with very high pileup
 - ➔ rate of fake tracks (fakes) increases
 - ➔ more tracks with large IP significant (tracking mistakes)
- pileup track selection
 - ➔ adapt tracking settings to pileup conditions
 - e.g. ATLAS: requiring 9 out of 11 hits, cut on “no Pixel holes”
 - ➔ suppresses fakes at expense of some efficiency



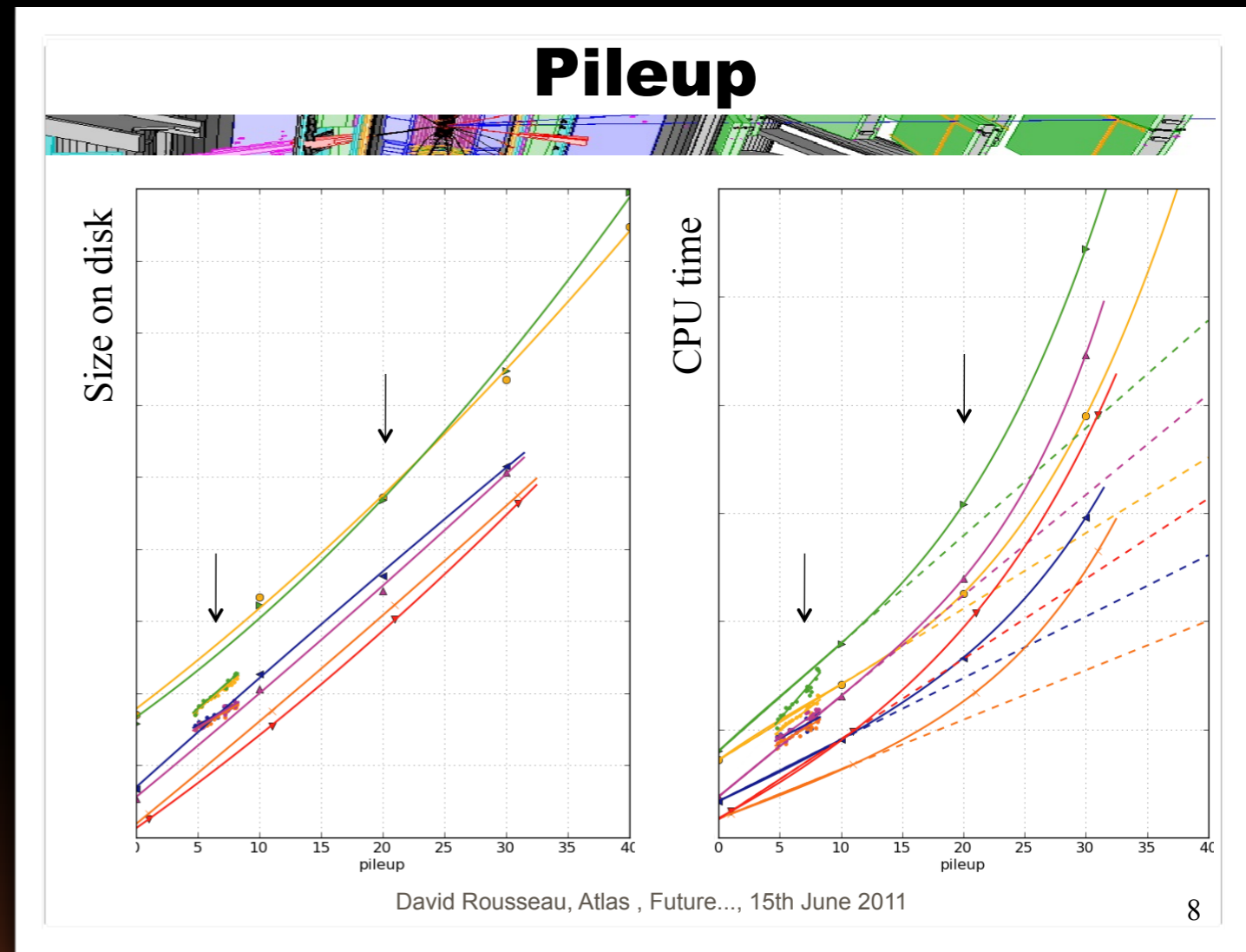
Tracking at High Luminosity (pp)

- small effects expected on tracking resolution
 - ➔ occupancy in pixels and strips still small
- exception is ATLAS TRT
 - ➔ rate of good hit (leading edge seen) drops
 - ➔ momentum resolution slowly deteriorates



Pileup and Computing Resources

- resource needs scale fast
 - ➔ tracking is a resource driver
- tracking principles:
 - ➔ combinatorial problem
 - ➔ naive scaling
 - like $\sim n!$
 - ➔ clever tracking strategies
 - dampen it to $\sim n^2$ or $\sim n^3$
- natural tension between
 - ➔ desire to maximize physics
 - ➔ requirement to stay within available resources



Reconstruction Strategy vs Pileup (ATLAS)

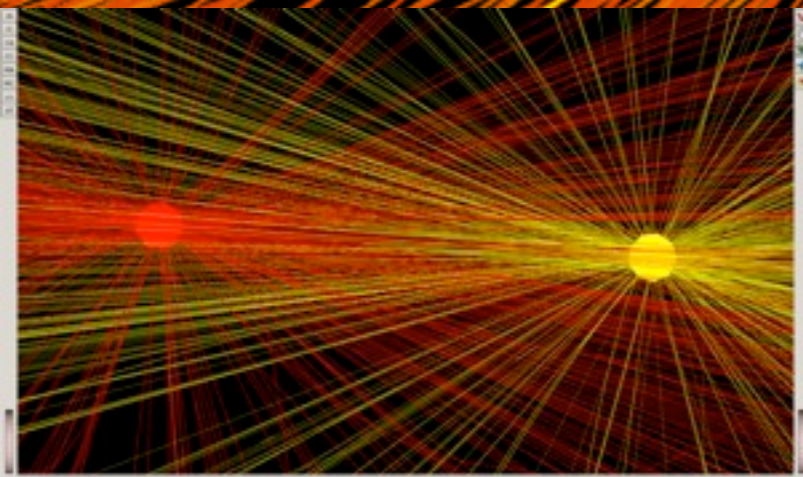
2009 / early 2010	commissioning Min.Bias	pt > 50 MeV open cuts, robust settings min. 5 clusters
2010 stable running < ~4 events pileup	low lumi physics program (soft QCD, b-physics, ...), b-tagging...	pt > 100 MeV min. 7 clusters
2011 pp running ~8 events pileup	focus more on high-pt physics (top, W/Z, Higgs), b-tagging...	pt > 400 MeV, harder cuts in seeding min. 7 clusters
Phase I upgrade including IBL 24-50 events pileup	high-pt physics, study new physics (I hope), b-tagging....	pt > 900 MeV, harder tracking cuts, min. 9 clusters
SLHC up to 100-200 events pileup	replace Inner Detector to cover very high luminosity physics program	further evolve strategy... R-o-I or z-vertex seeding, reco. per trigger type, GPUs

- ➔ requirements on tracking evolves with physics program
- ➔ different luminosity regimes require different working points

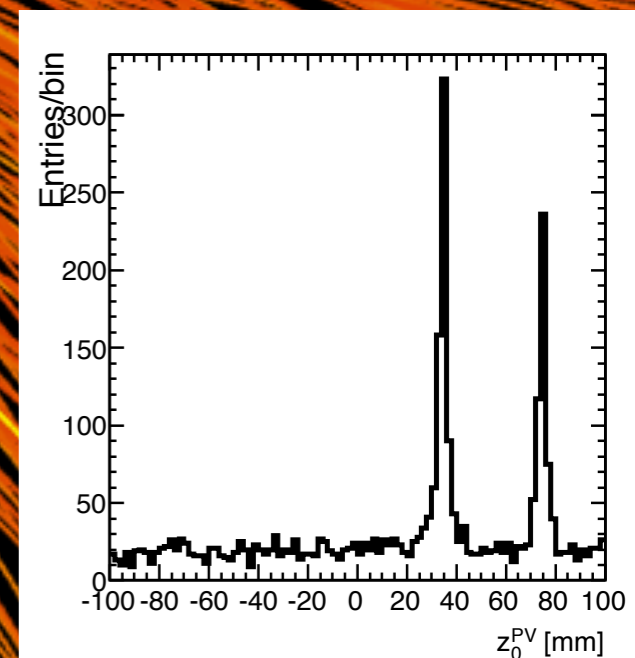


Tracking in Heavy Ions

- What if the tracker suddenly looks like this ?

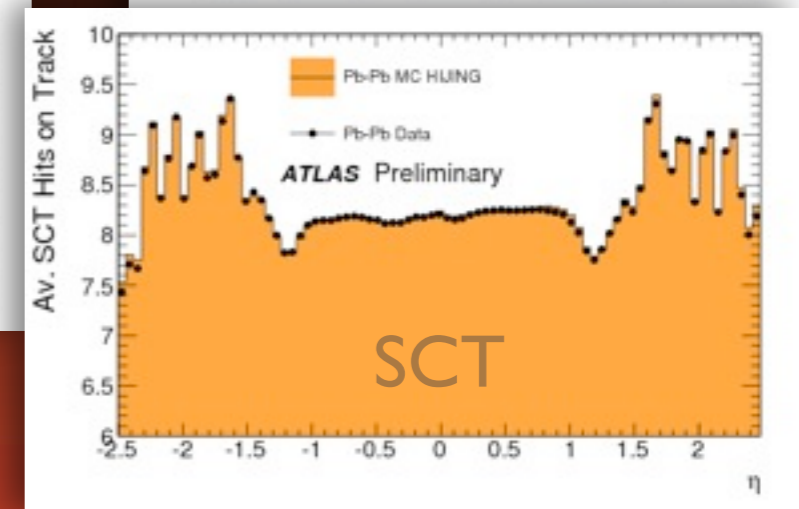
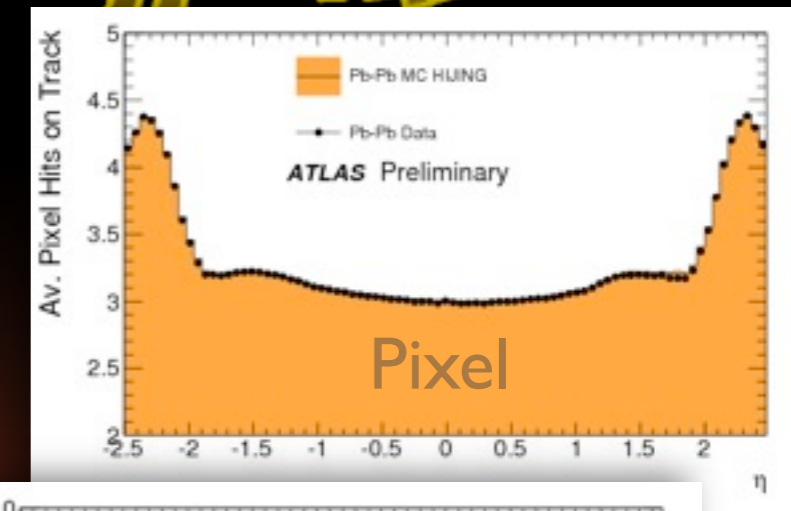
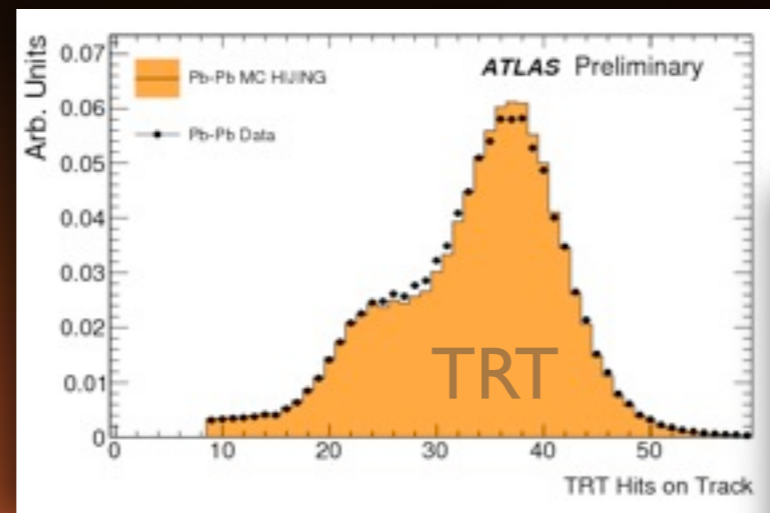
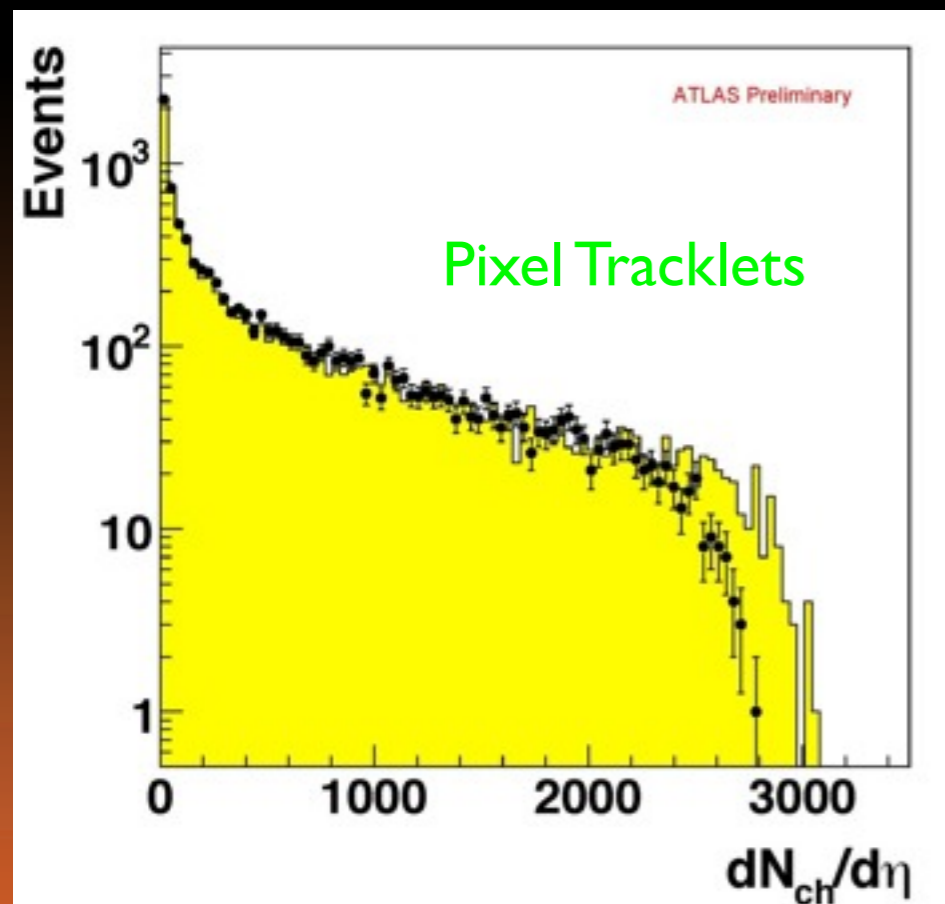
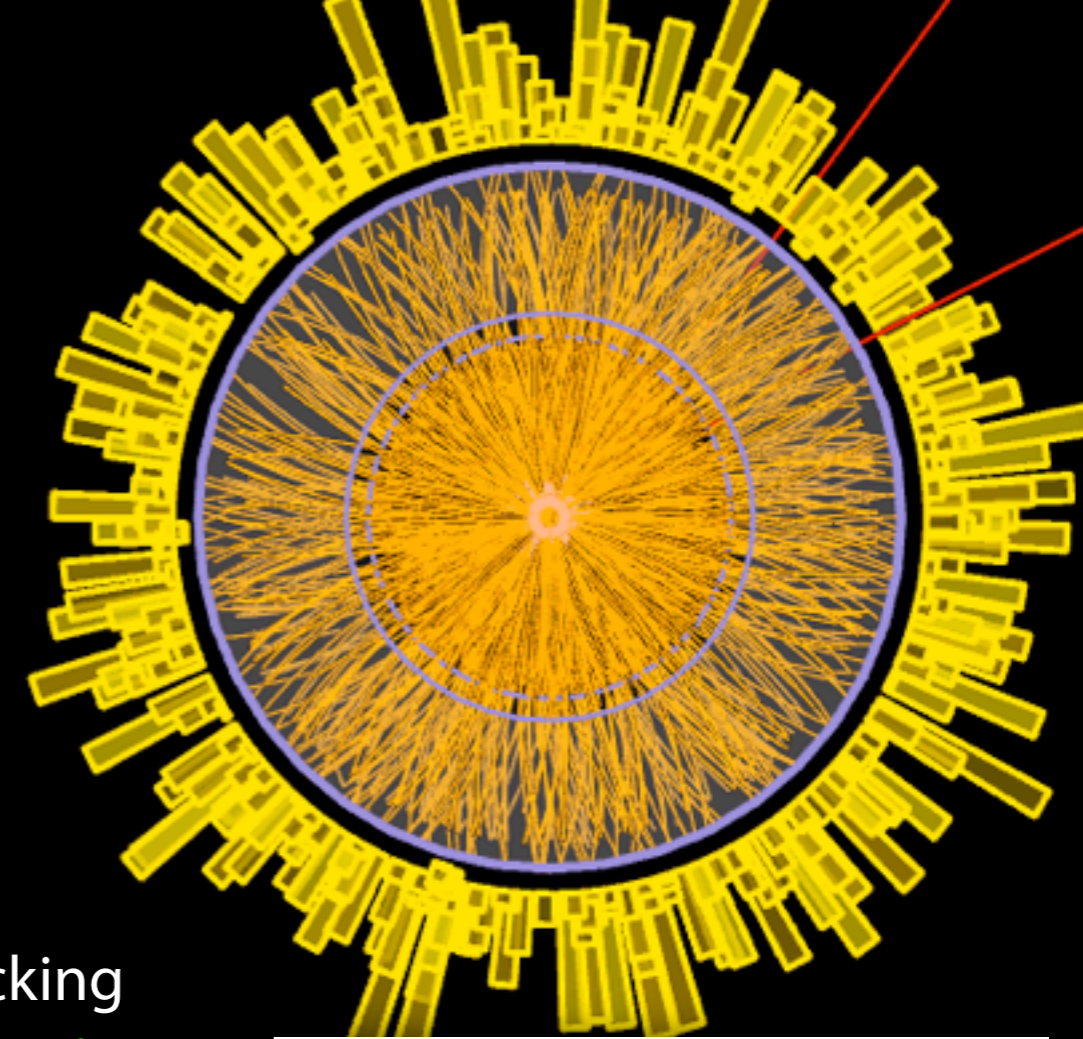


2 central Pb-Pb events pileup,
result was a timeout crash in Tier-0

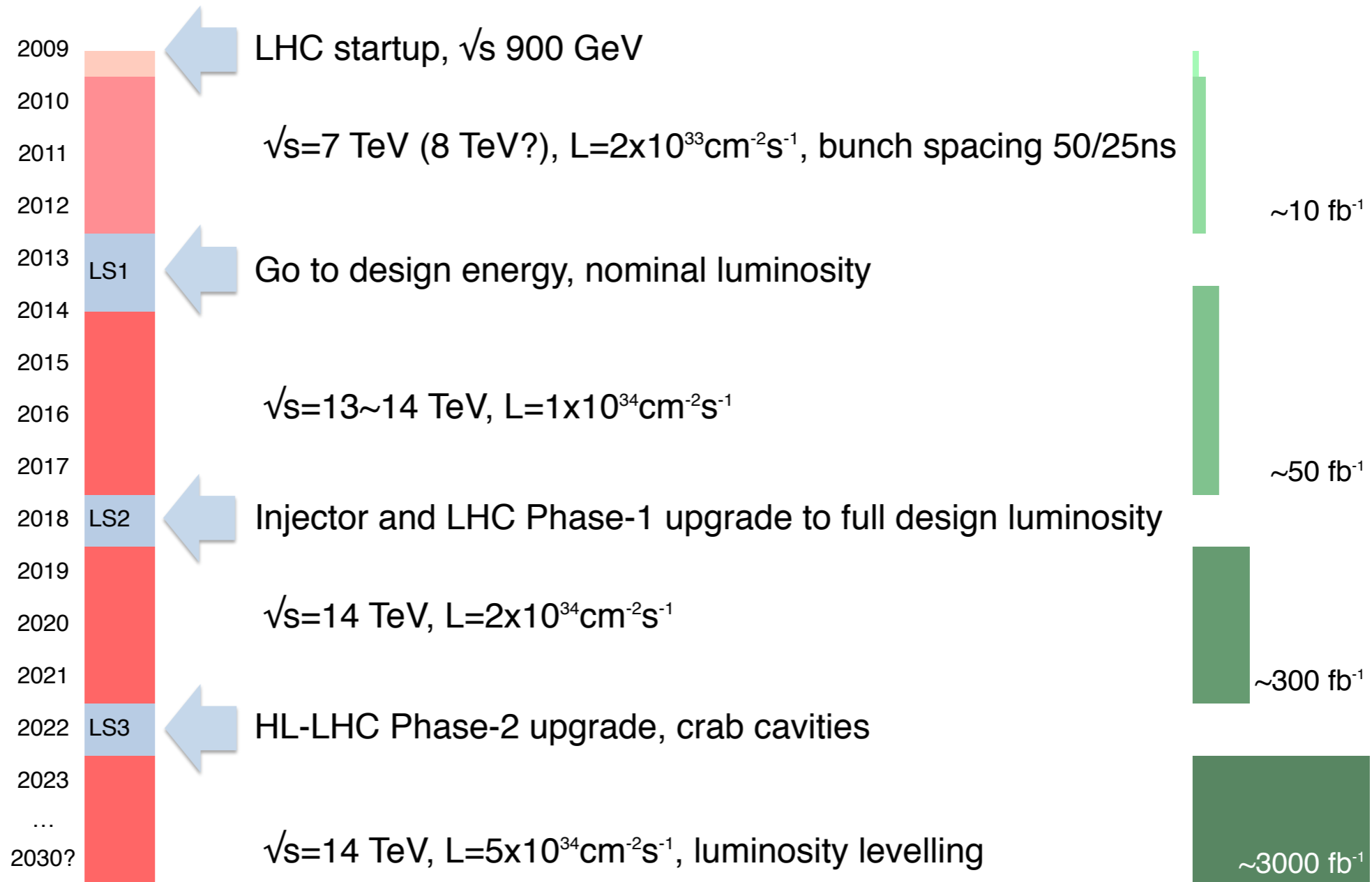


Heavy Ion Tracking

- high multiplicity tracking
 - ➔ adapt seed finding (z vertex constraint to save CPU)
 - ➔ tighten hit requirement to control fakes in central events (similar to sLHC setup)
- excellent tracking performance
 - ➔ good testing ground for high occupancy tracking
 - ➔ can study performance vs “centrality” (occupancy)



LHC draft plan



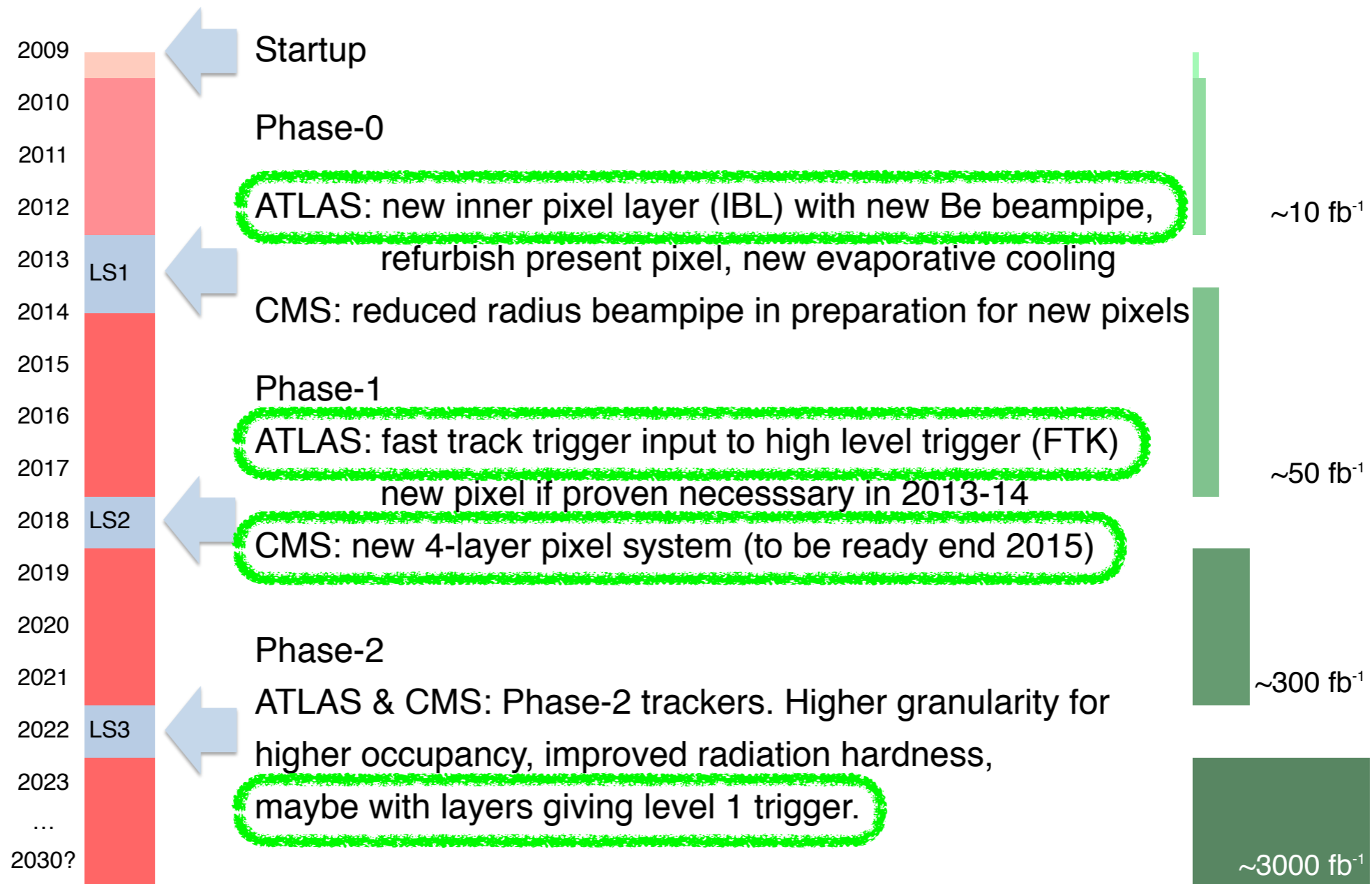
23 July 2011

Joint ECFA-EPS, Pippa Wells, CERN

14

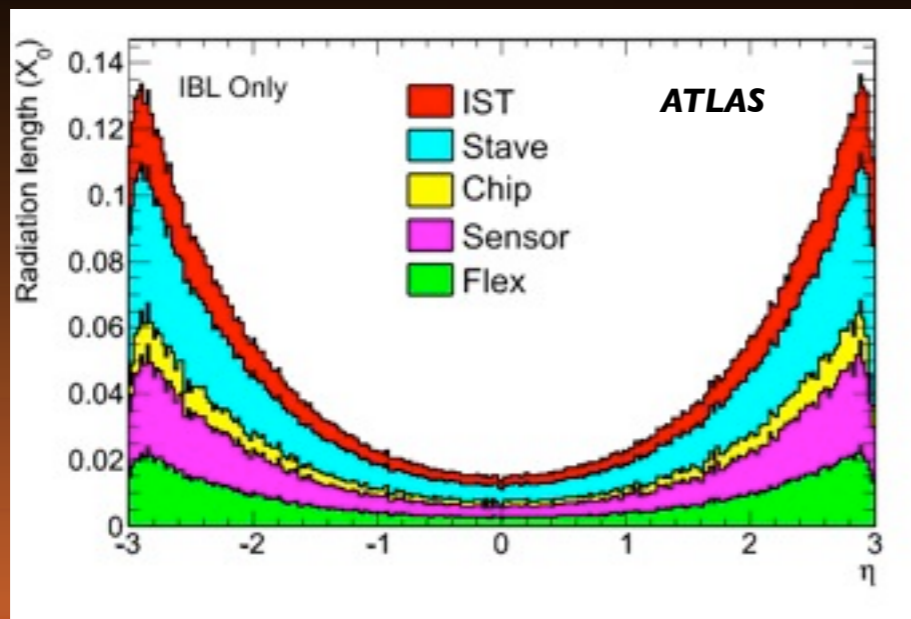
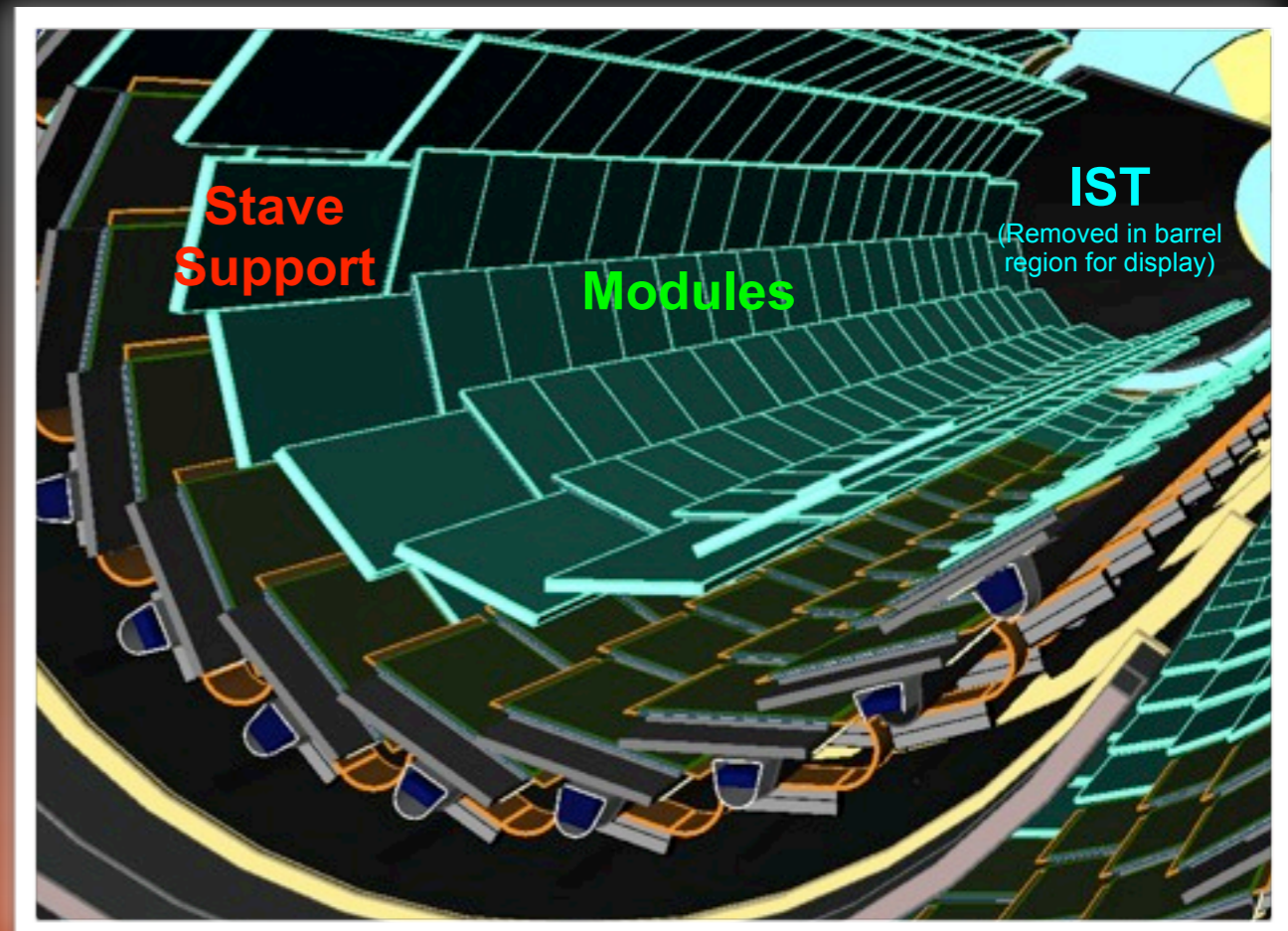
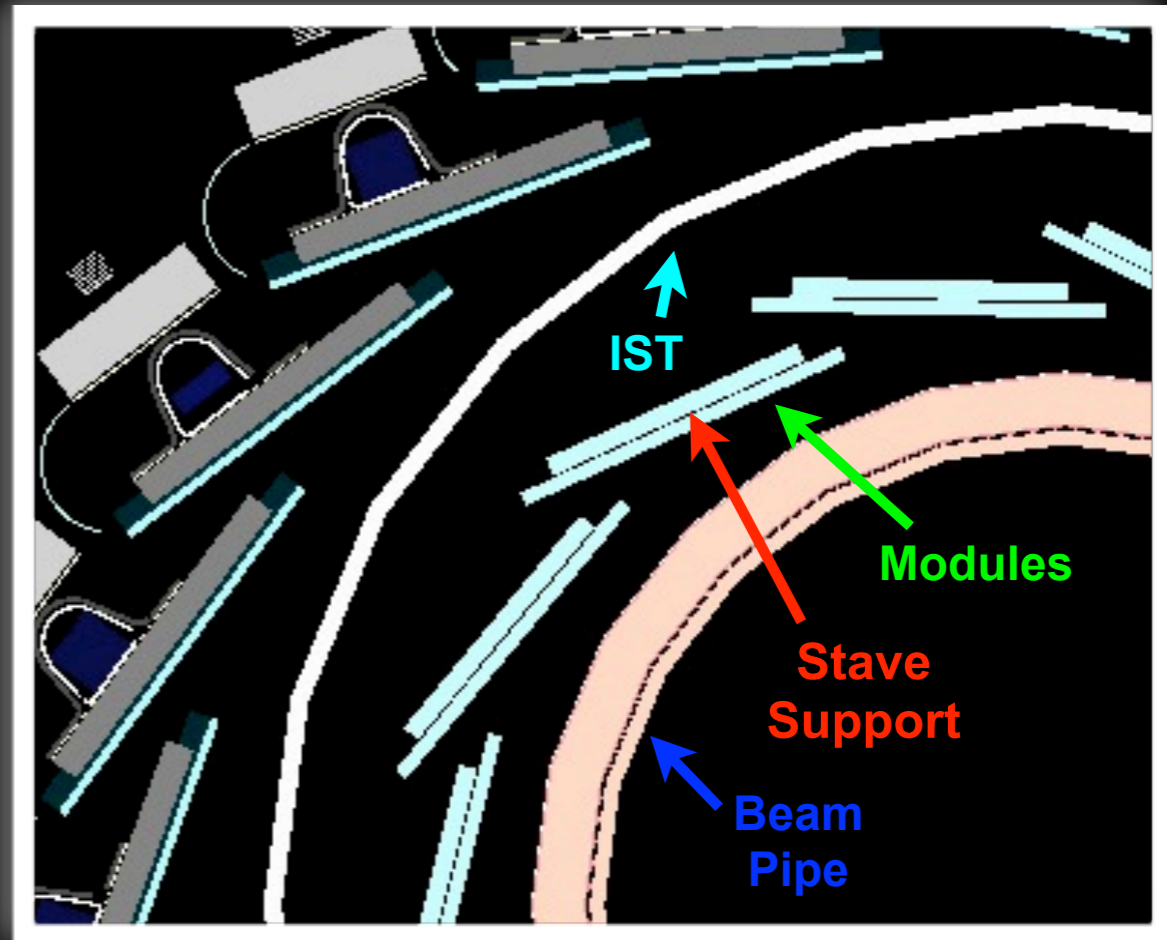


Tracker related upgrades



ATLAS Upgrade: IBL

- **I**nserable **B-L**ayer
 - ➔ 4th Pixel layer
 - ➔ smaller beam pipe ($R_{\min} = 25 \text{ mm}$)
 - ➔ IBL material adjusted to 1.5% X_0
 - ➔ smaller z pitch (250 μm)
- installation next shutdown
 - ➔ 2013/2014
 - ➔ ready for 14 TeV running
 - ➔ peak luminosities of $2 \cdot 10^{34} \text{ cm}^{-2}\text{s}^{-1}$
 - ➔ 25-50 pileup events



Tracking Performance with no Pileup

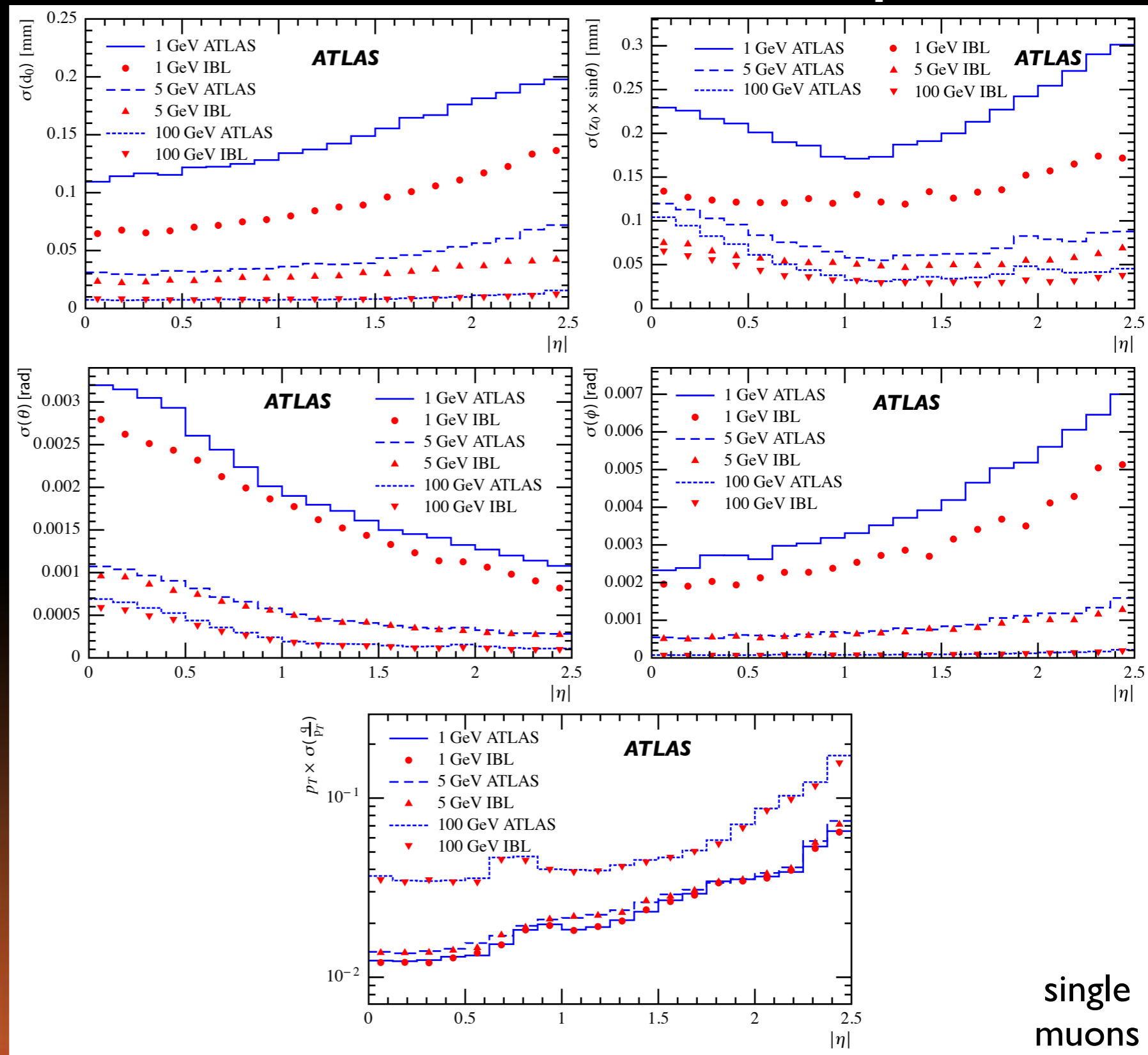
- expected results

- ➔ smaller radius
- ➔ small z pitch
- ➔ less material between first and 2nd layer
- ➔ track length ~ same

- improvements

- ➔ better d_0 resolution
- ➔ better z_0 resolution
- ➔ θ and ϕ improved at low- p_T
- ➔ momentum resolution ~ unchanged

- as expected !



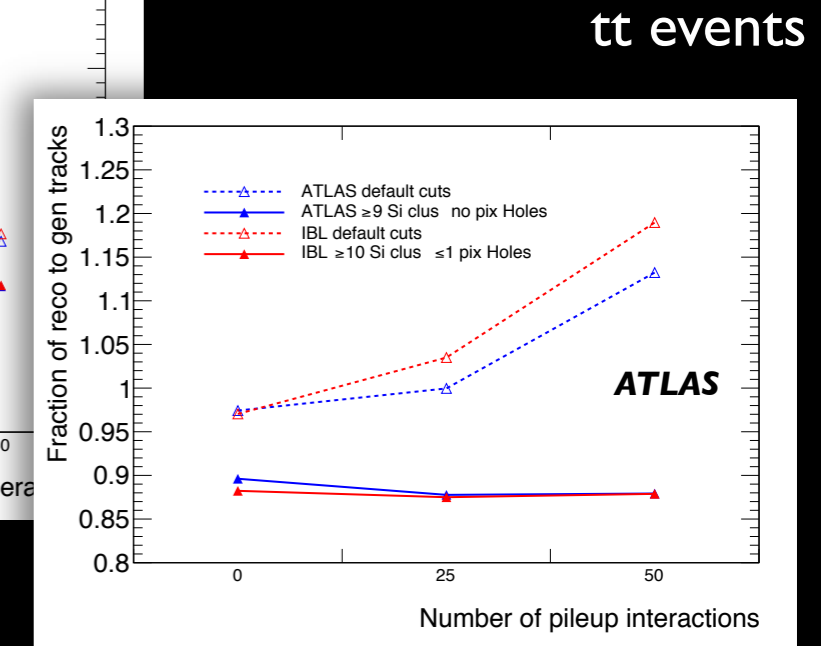
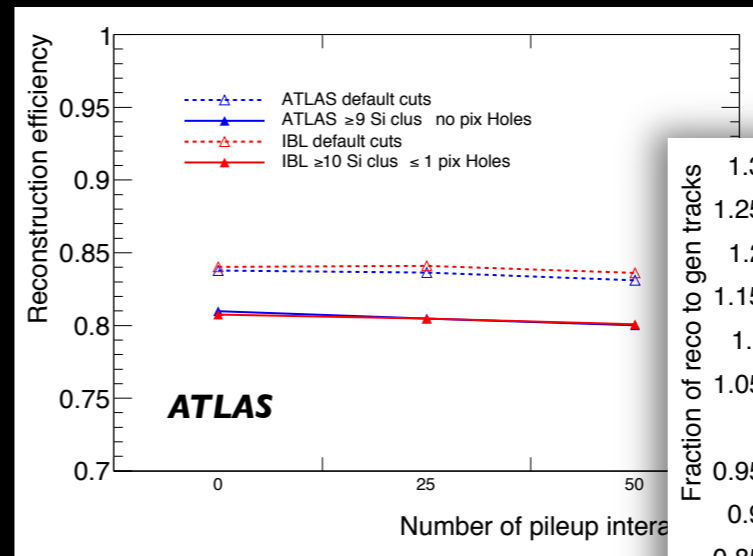
single muons



Tracking and Vertexing with High Pileup

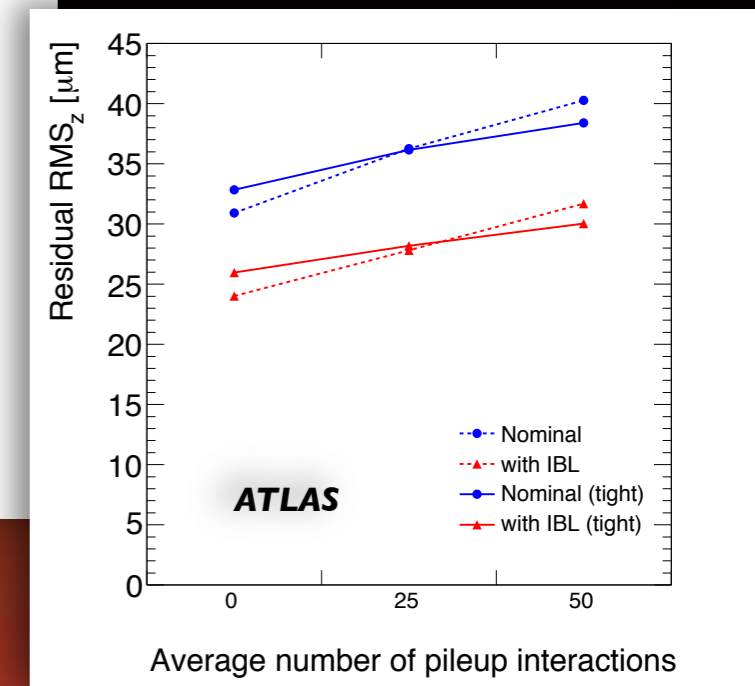
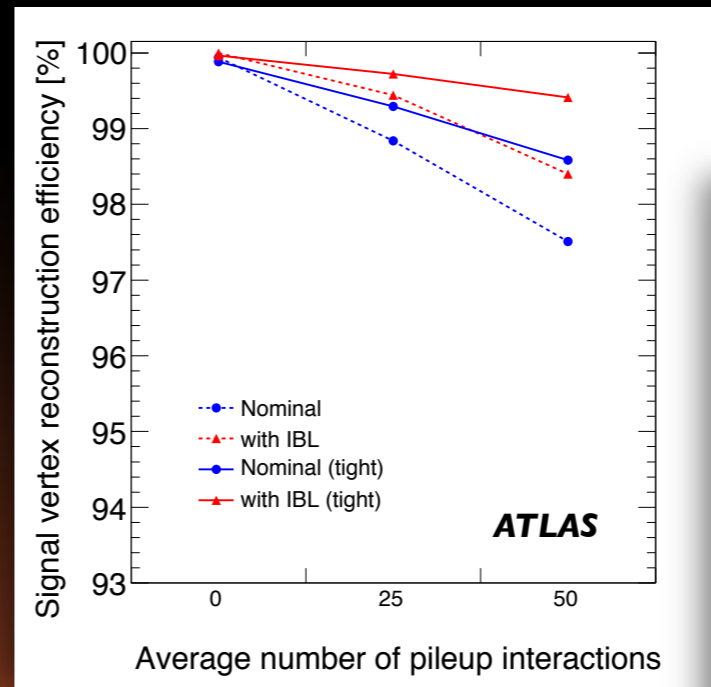
- pileup selection with IBL

- ➔ similar to current ATLAS
- ➔ ≥ 10 IBL+Pixel+SCT hits, ≤ 1 pixel hole
- ➔ benefit from additional layer
- ➔ leaves room for eventual inefficiencies in b-layer (tracking robustness)



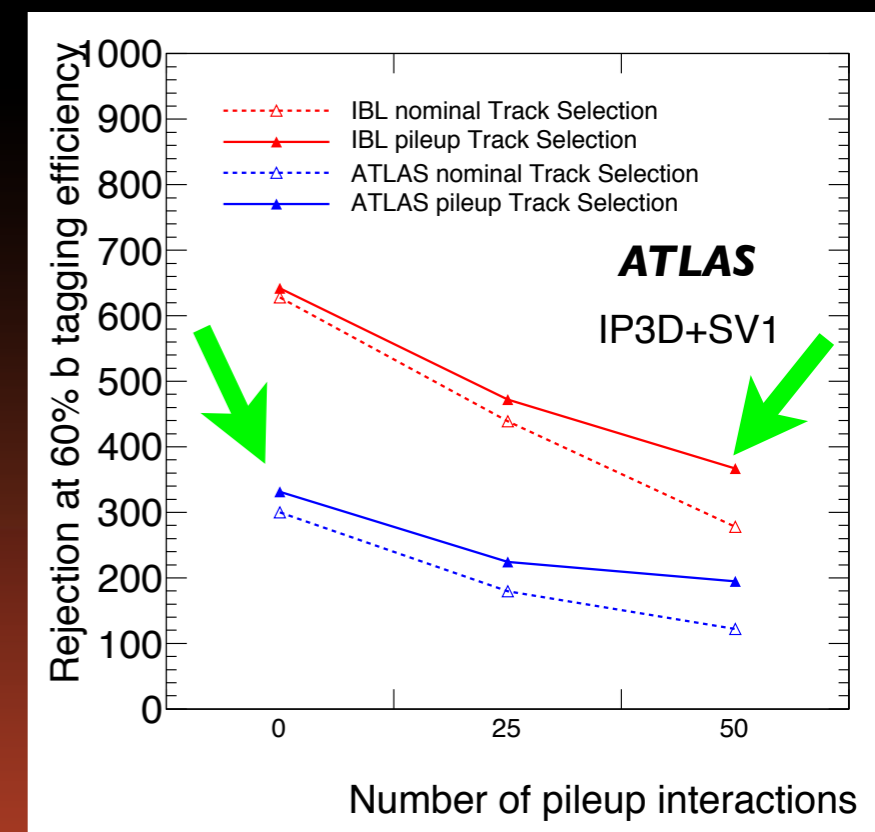
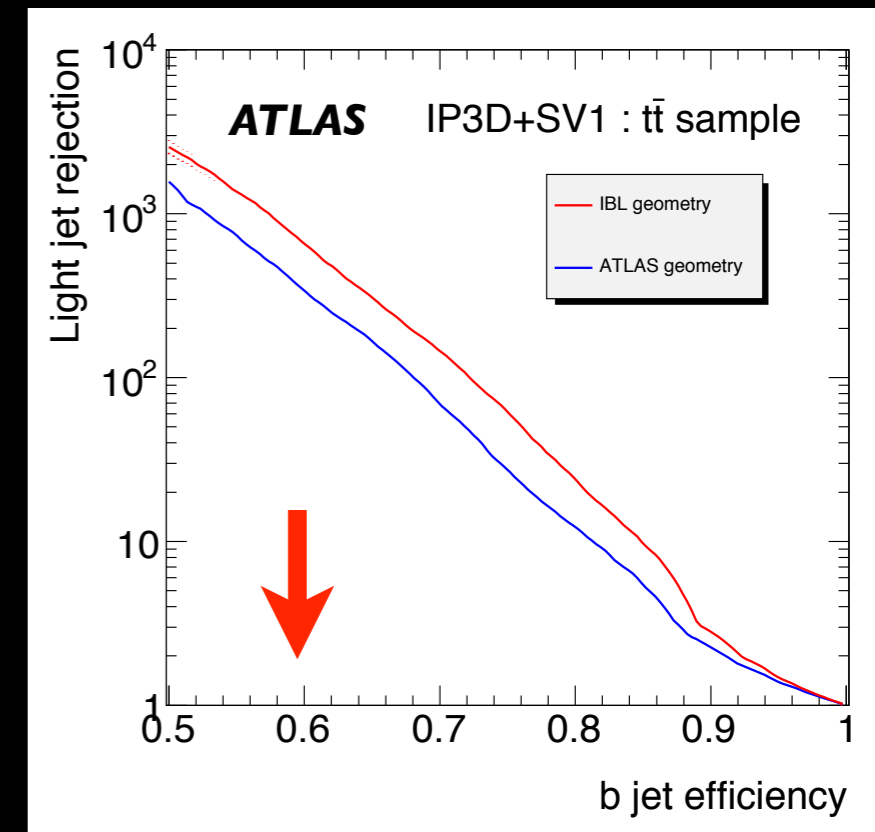
- vertexing with pileup

- ➔ pileup effects visible
- ➔ with IBL gains in resolution and vertex tail fraction as well with pileup
- ➔ signal vertex efficiency affected
- ➔ pileup selection better overall



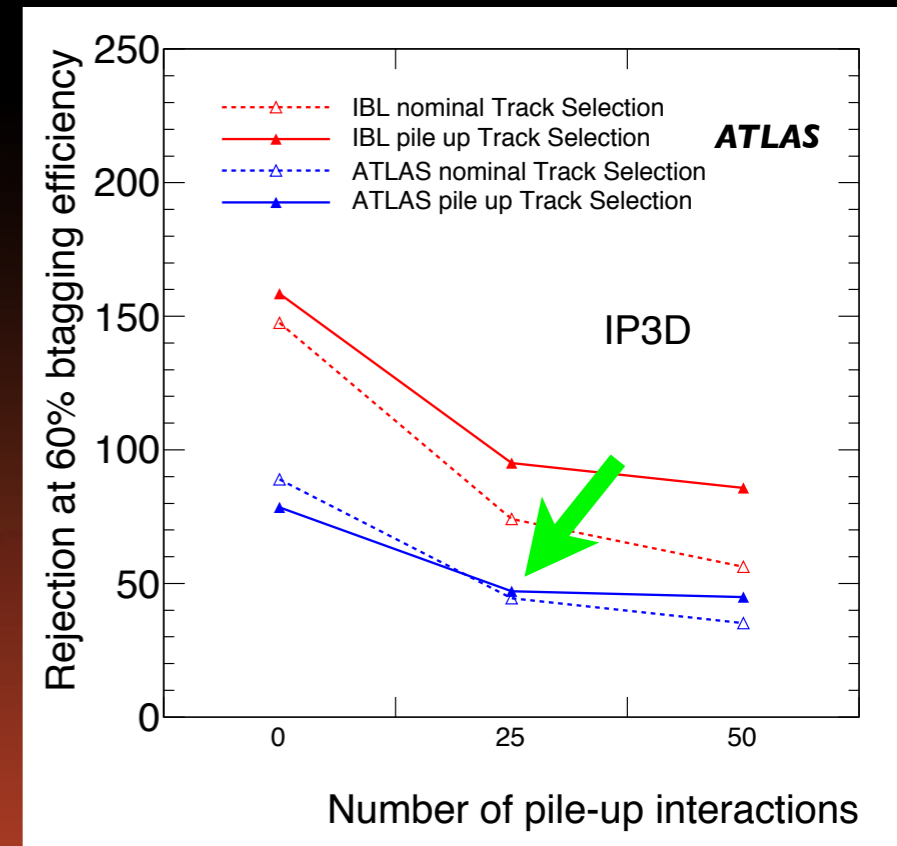
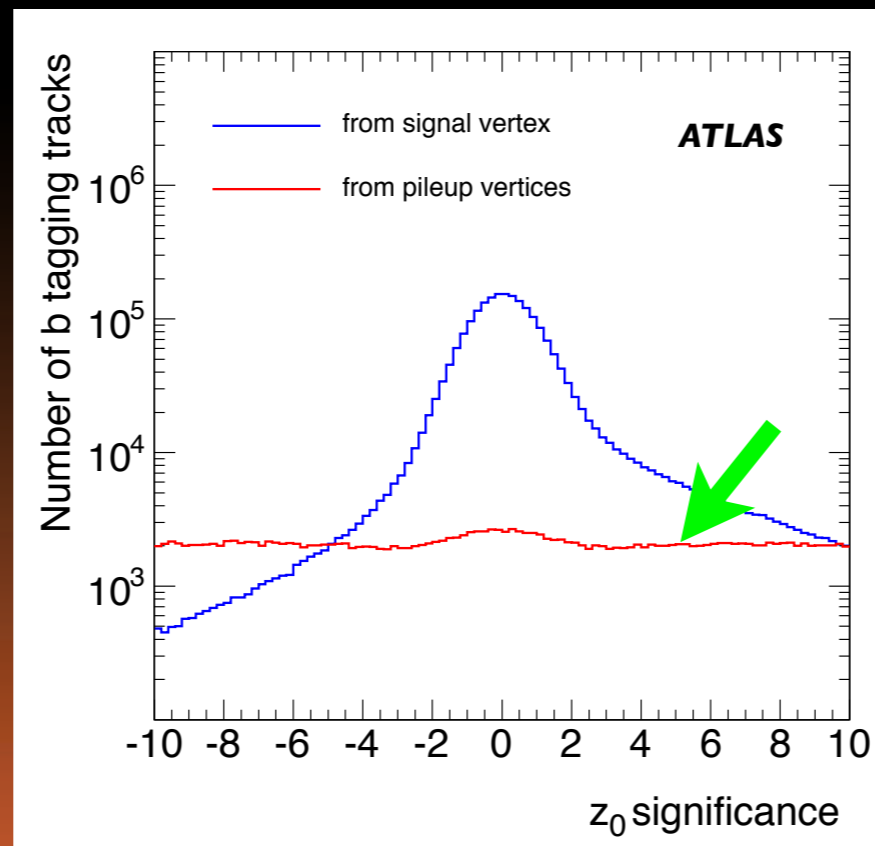
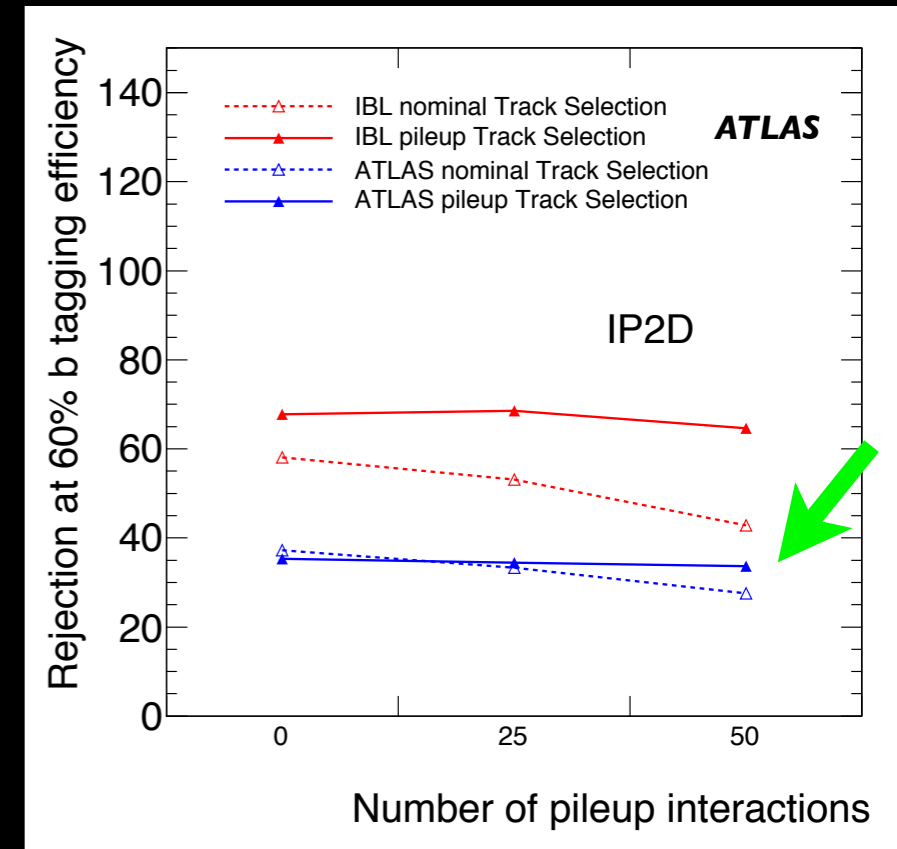
b-Tagging with IBL and Pileup

- example state of the art b-tagging
 - ➔ “IP3D” $\sim d_0 \oplus z_0$ impact significance likelihood
 - ➔ “IP3D+SV1” \sim adding secondary vertex information
- pileup affects b-tagging in many ways
 - ➔ additional jets and fake jets from in/out of time pileup
 - restrict to truth jets to get comparable results
 - real data: can use e.g. Jet-Vertex-Fraction
 - ➔ close-by pileup vertices
 - additional b-tag tracks
 - lead to significant z_0 offsets affecting IP3D
- good performance with IBL and pileup
 - ➔ as good or better as for current ATLAS without pileup



b-Tagging with Pileup

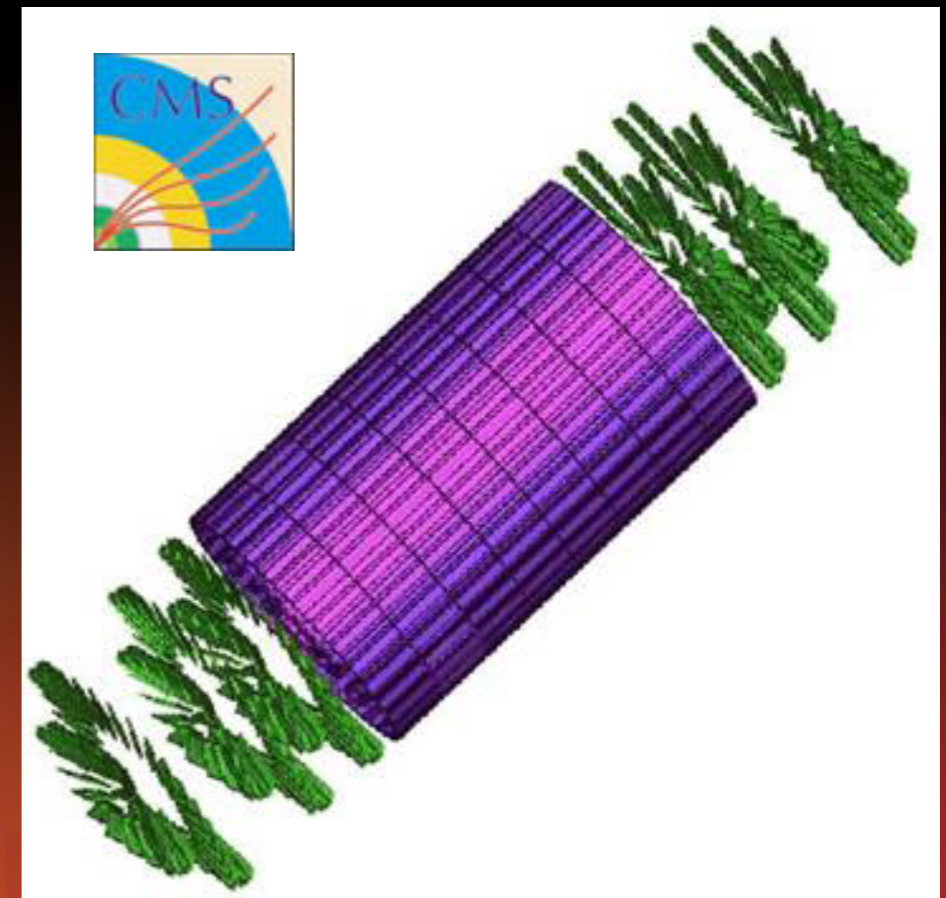
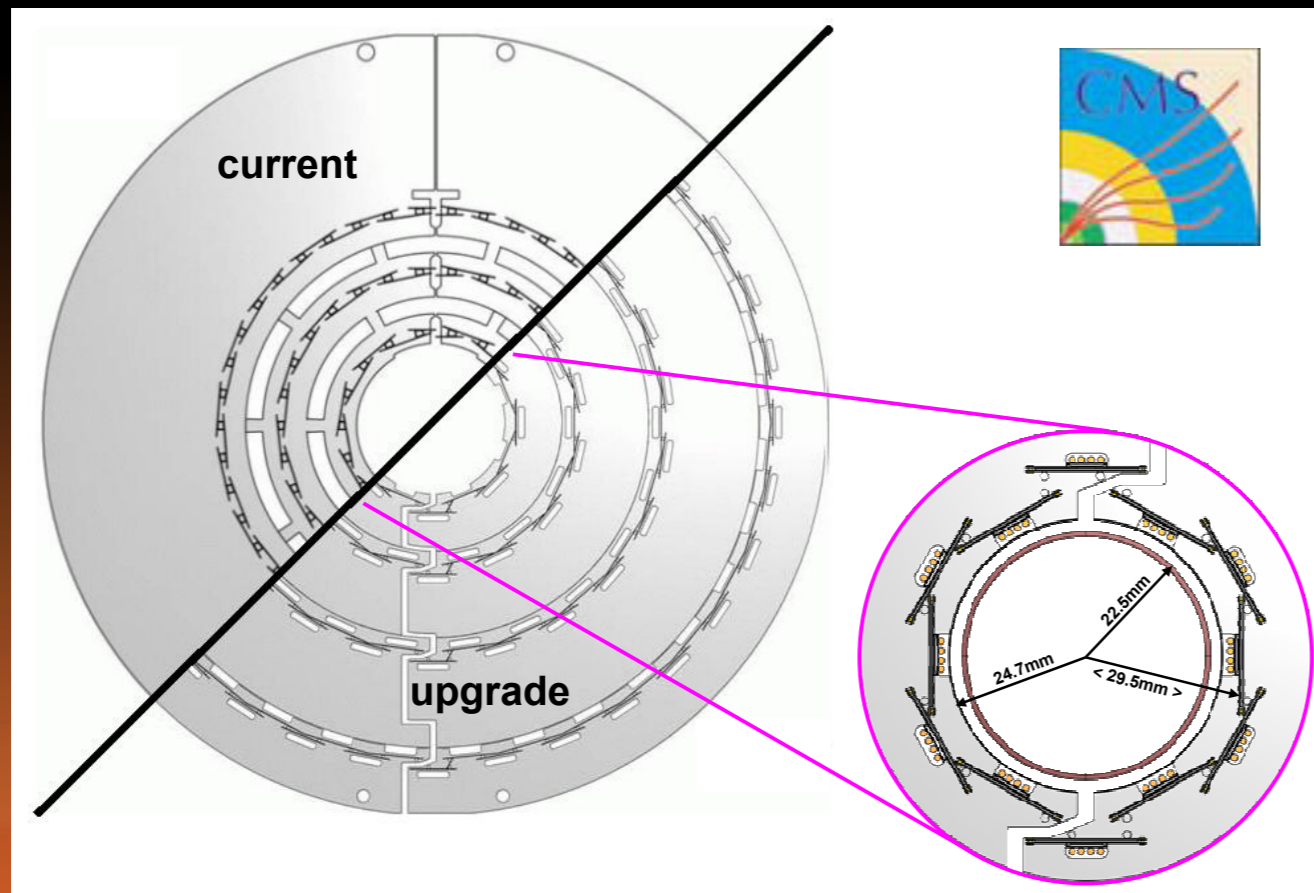
- performance could degrade fast
 - ➔ especially IP3D is very sensitive to tracks from nearby pileup vertices
 - ➔ significant z offsets due to nearby pileup vertices
 - needed to add cut to veto pileup tracks:
 - $dz < 3.8\sigma$ if $d0 < 2\sigma$**
 - ➔ IP2D (R ϕ only) is much more "stable"



CMS Pixel Upgrade

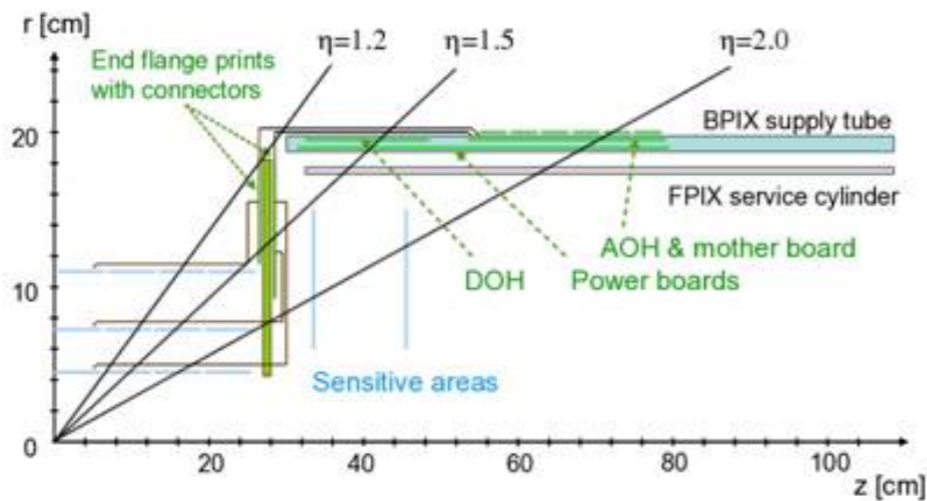
- goals of the upgrade

- ➔ replace 3 layer, 2x2 disk system with a 4 layer, 2x3 disk system
 - hence 4 space points instead of 3
- ➔ CO₂ cooling and move material to larger eta
 - significantly reduce X/X_0
- ➔ reduce radius of innermost layer
 - better impact resolution
- ➔ readout upgrade to be able to operate up to $2 \cdot 10^{34}$ occupancies



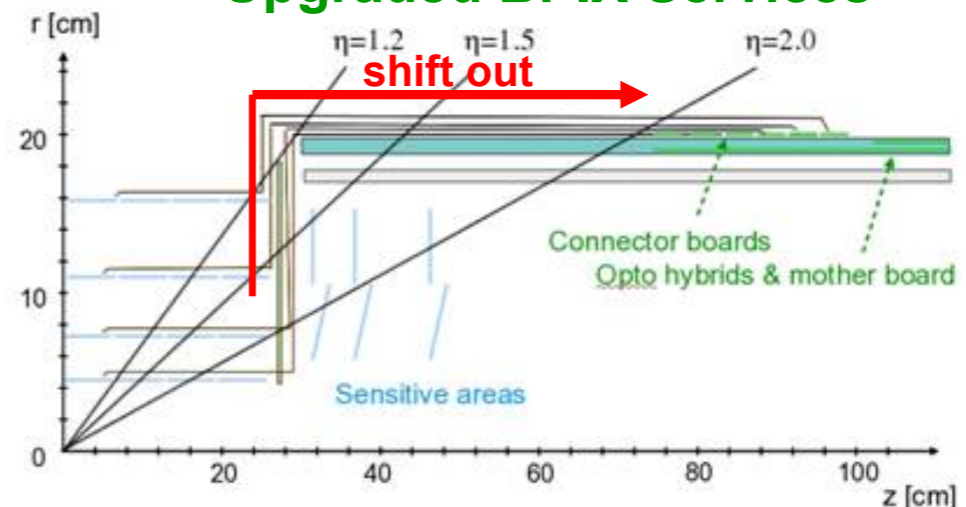
Shift Material out of Tracking Region

Current BPIX Services



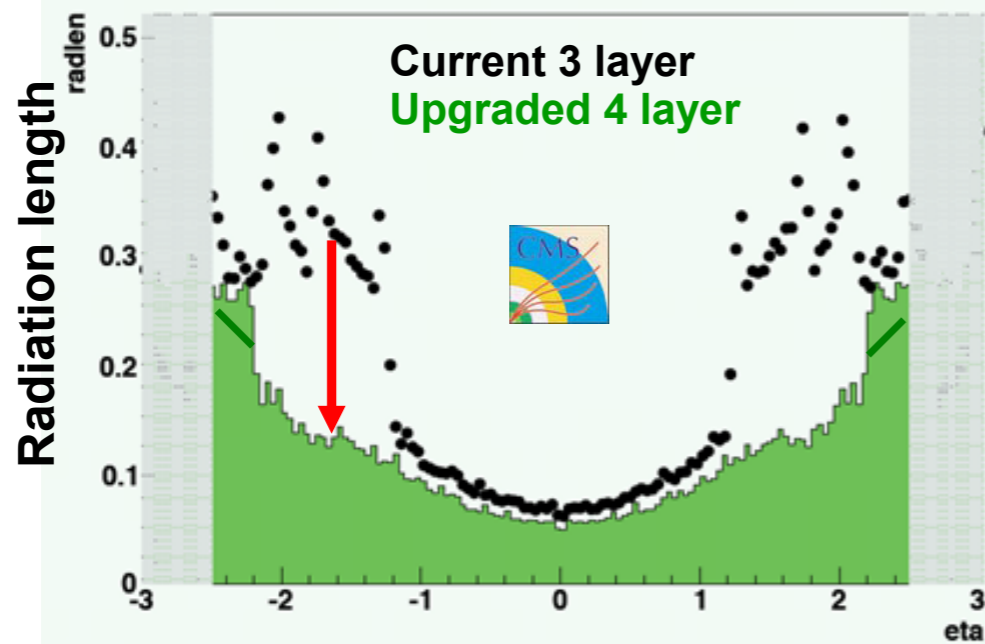
$\eta < 2.2$: weight = 16.9 Kg (3 layer)

Upgraded BPIX Services



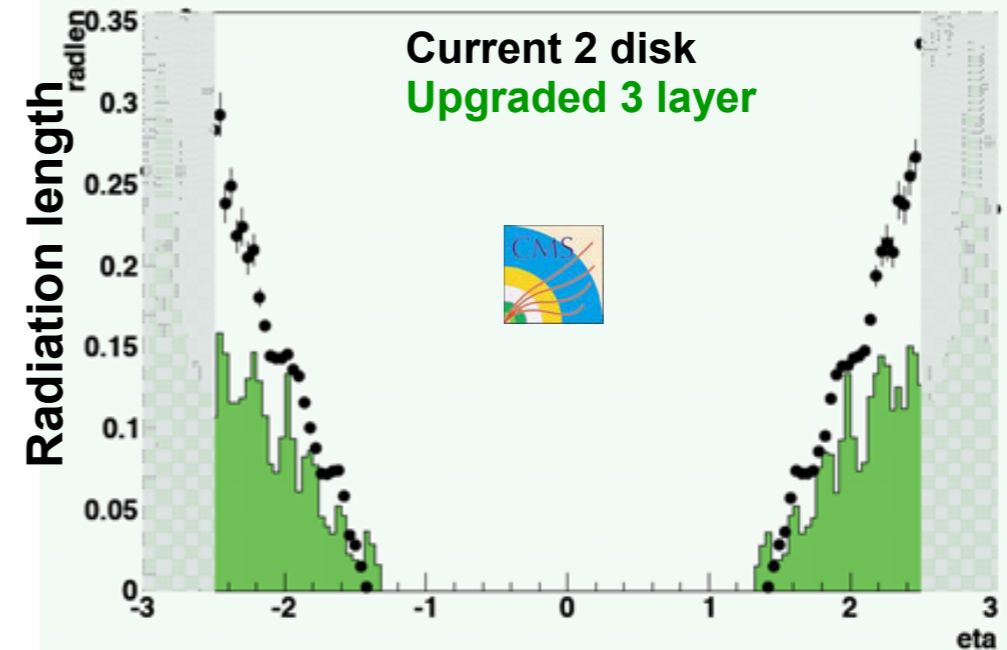
$\eta < 2.2$: weight = 6.5 Kg (4 layer)

Pixel Barrel



Current 3 layer
Upgraded 4 layer

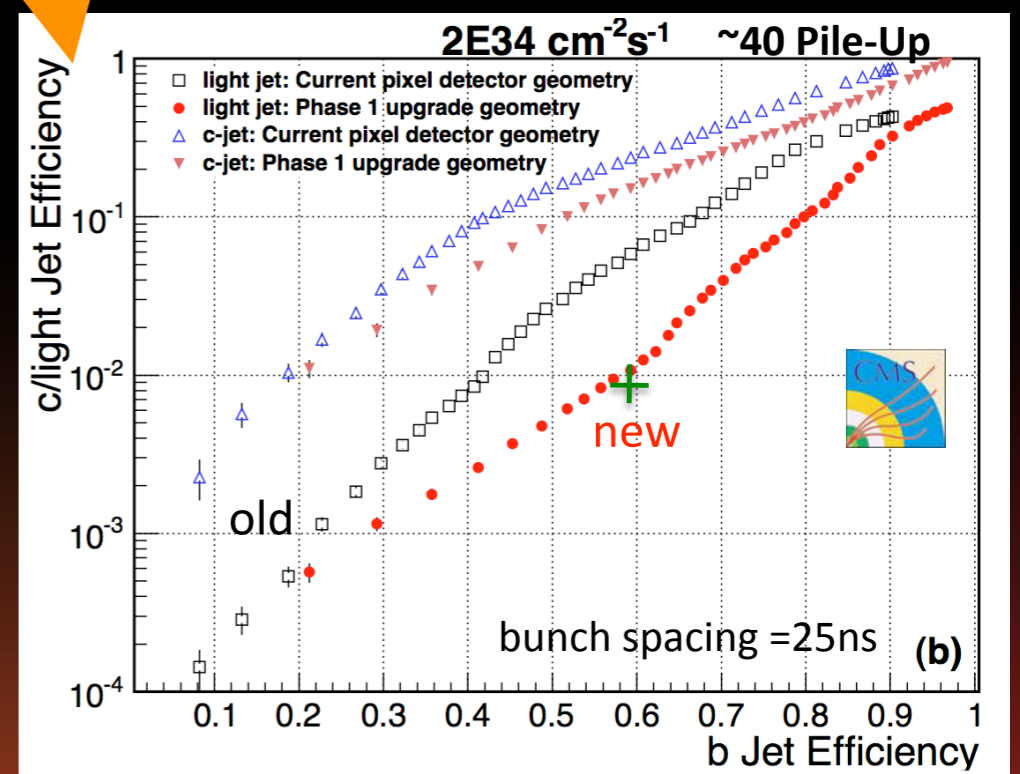
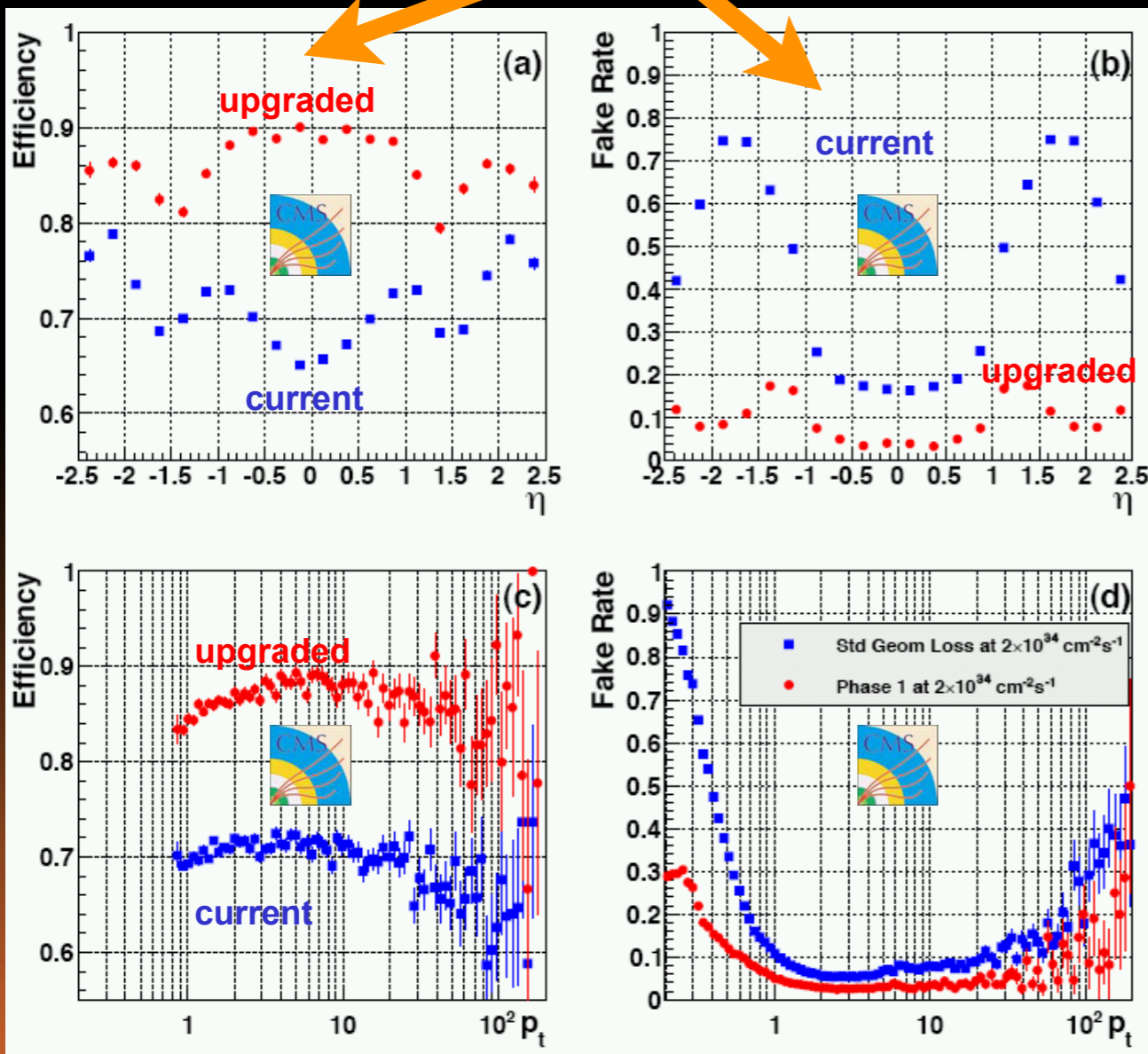
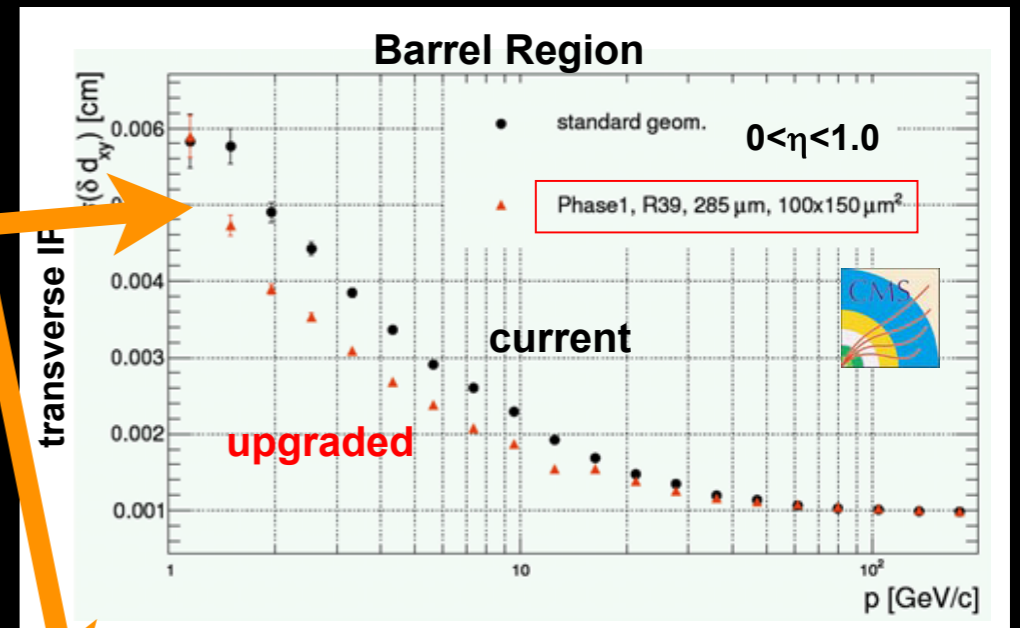
Pixel Forward



Current 2 disk
Upgraded 3 layer

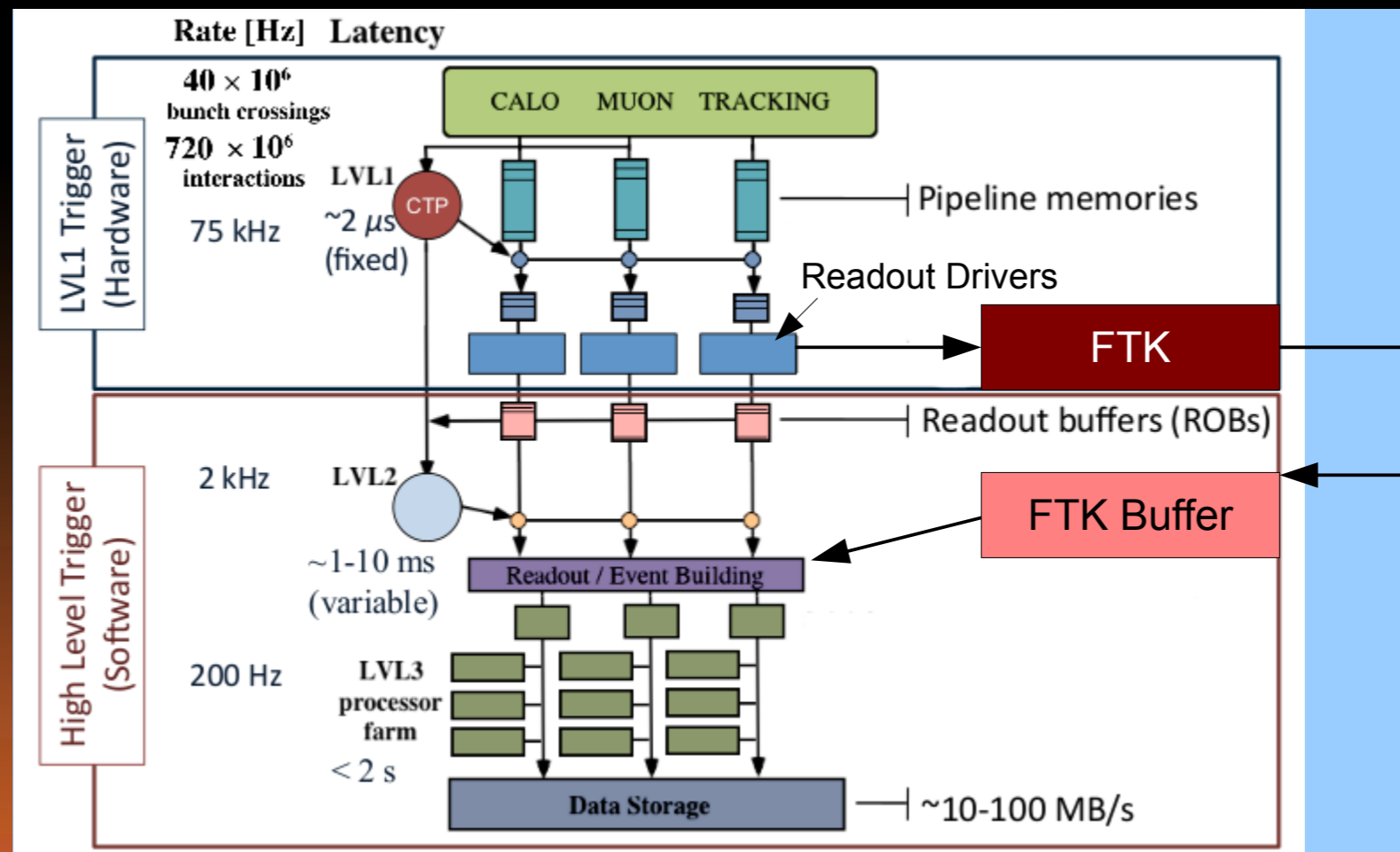
Effect on Physics Performance

- huge gains expected
 - ➔ especially for IP resolution and b-tagging
 - ➔ improved track seeding using 4 Pixel hits



ATLAS Hardware Trigger Tracking (FTK)

- goal is to provide high quality tracks at input to High Level Trigger
 - ➔ FTK runs at nominal 100 kHz Level-1 trigger rate
- physics motivation
 - ➔ b and τ tagging, lepton isolation, improve Level-2 rejection at high lumi.
- requires hardware system with special readout links



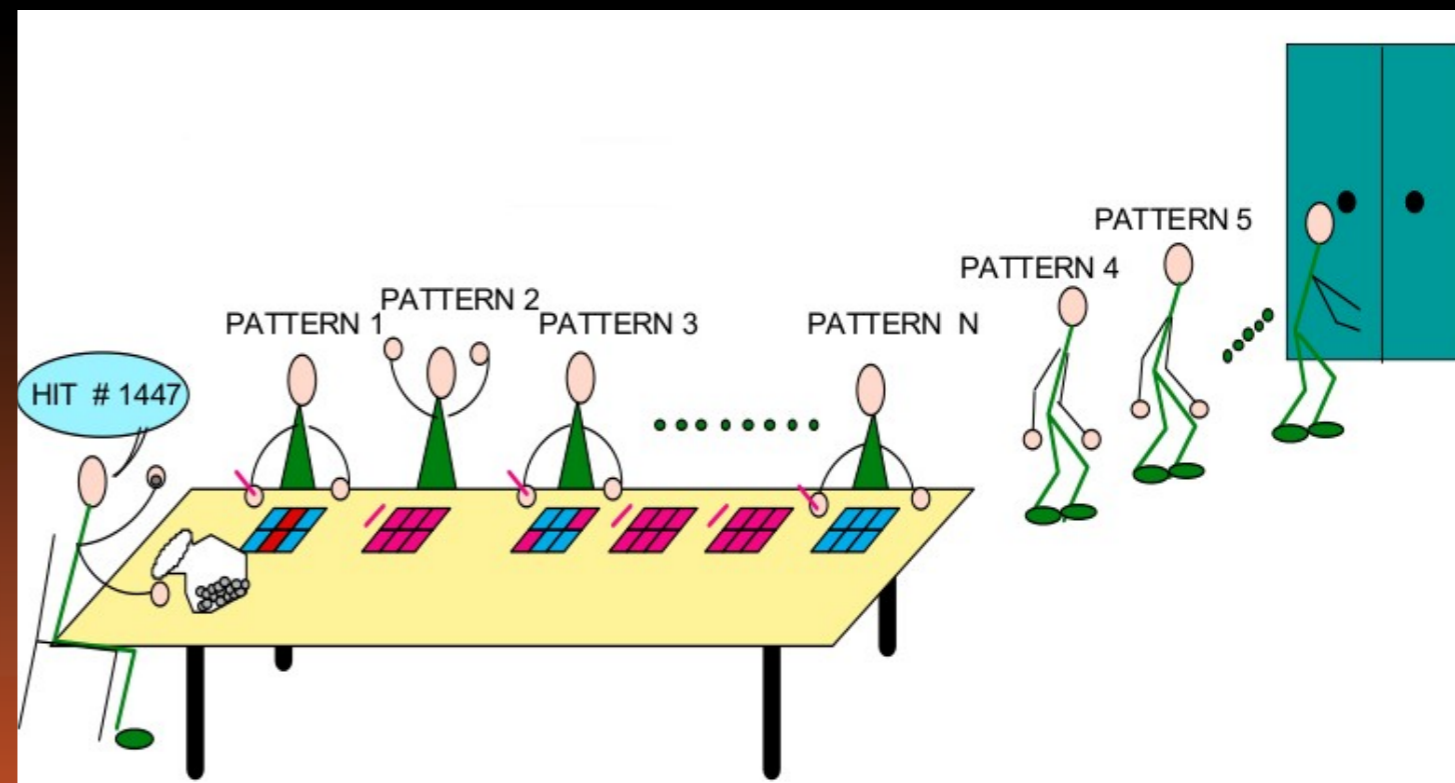
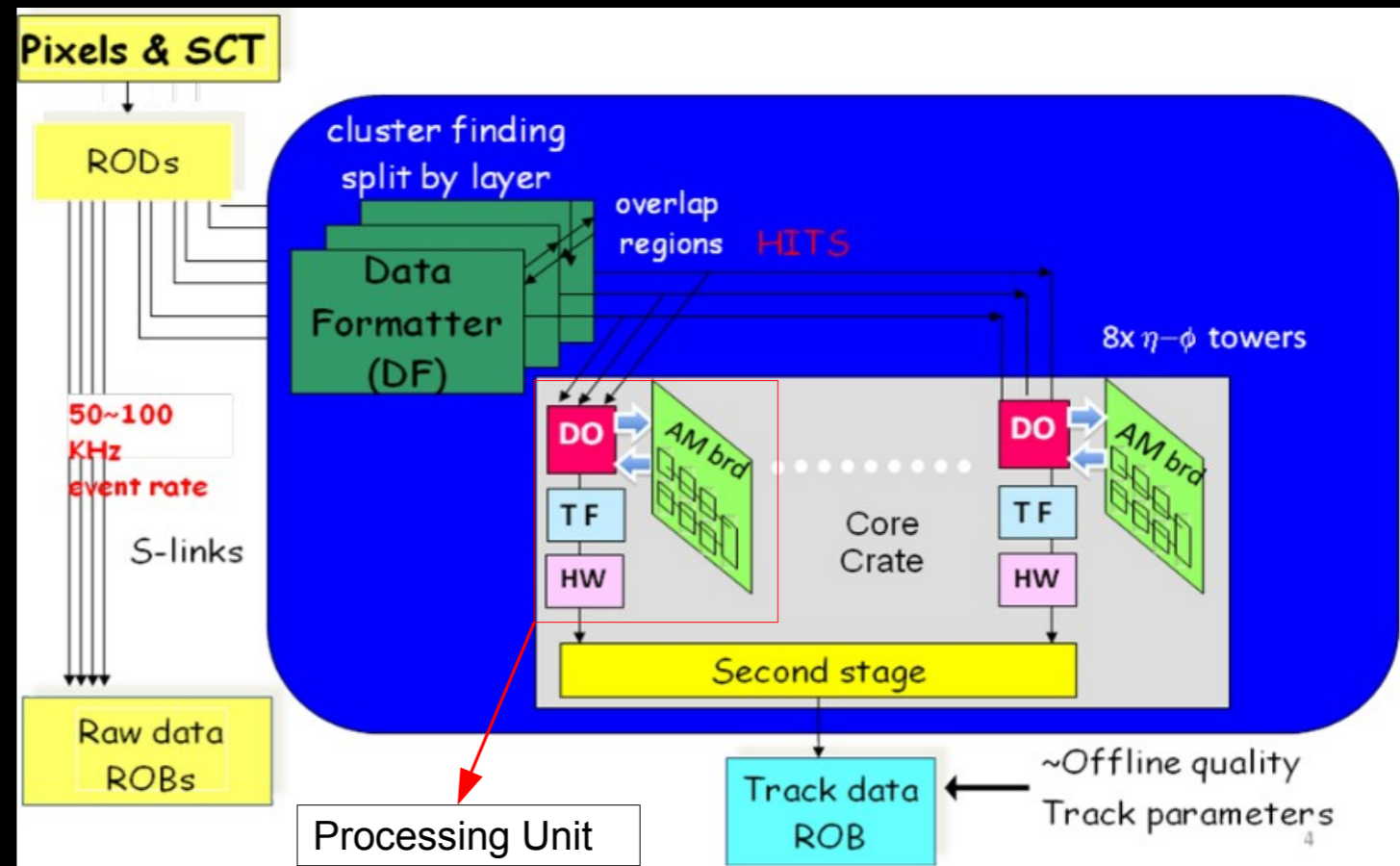
FTK - Overview

- architecture follows CDF

- ➔ Data formatter
 - clustering, routing to η - ϕ towers
- ➔ Data organizer (DO)
 - stores hits, communicates between pattern recognition and track fitting
- ➔ Associative Memory (AM) board
 - Pattern recognition
- ➔ track Fitter (TF)
 - FPGA-based track fitting

- associative memory

- ➔ millions of predefined hit patterns
- ➔ hits are evaluated against all patterns in parallel, leading to high timing gains !



FTK - Overview

- fast track fitting

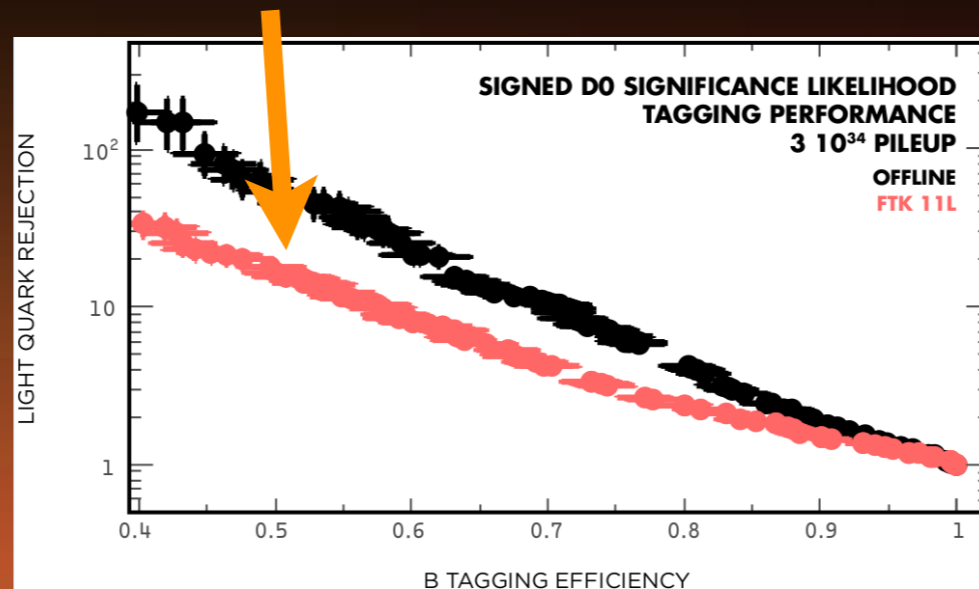
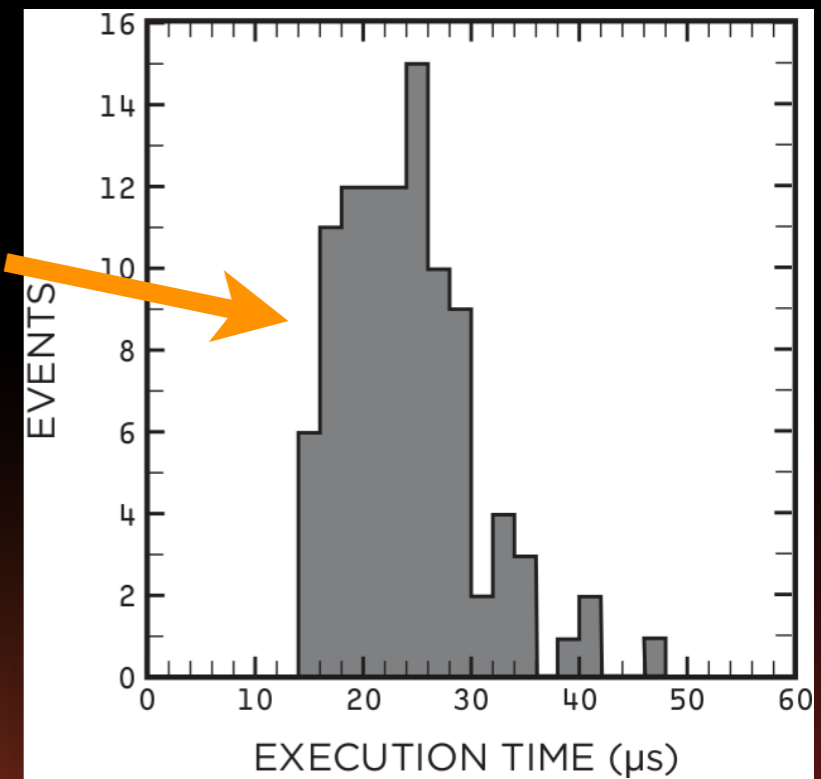
- ➔ divide detector in regions
- ➔ approximate track fit by a linear equation
- ➔ determine constants using full resolution in those regions (from offline)
- ➔ implement in FPGA chips, track fit ~ 1 nsec (full ~ 1 msec)

$$p_i = \sum_j c_{ij} \cdot x_j + q_i$$

Track parameters and χ^2 components $\rightarrow p_i$
 Hit coordinates $\rightarrow x_j$
 Constants $\rightarrow c_{ij}, q_i$

- performance

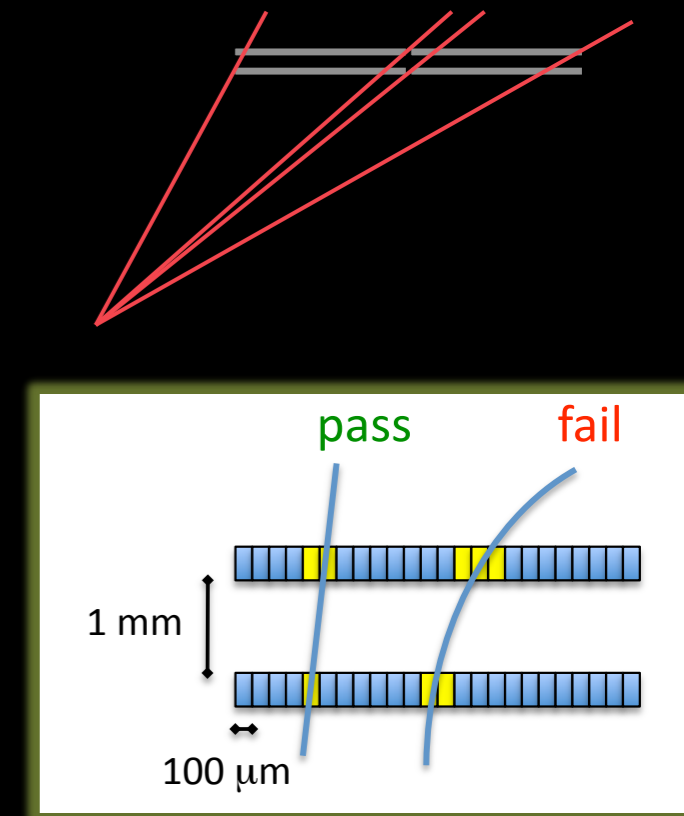
- ➔ timing for $H \rightarrow bb$ with 75 pileup, full scan, $p_T > 1$ GeV
- ➔ tracking efficiency $> 90\%$ compared to offline
- ➔ approximated track fit limits resolution of fit
- ➔ example: b-tagging performance at 75 pileup



CMS Track Trigger for Phase-2

- R&D for a track trigger

- ➔ pushes ideas similar to FTK to bring tracking to Level-1 (!)
- ➔ motivation is to keep Level-1 rate at 100 kHz
 - confirm muons in tracker
 - electron/photon isolation with tracks
- ➔ requires $\sim 6 \mu\text{sec}$ latency (length of ECAL pipelines)

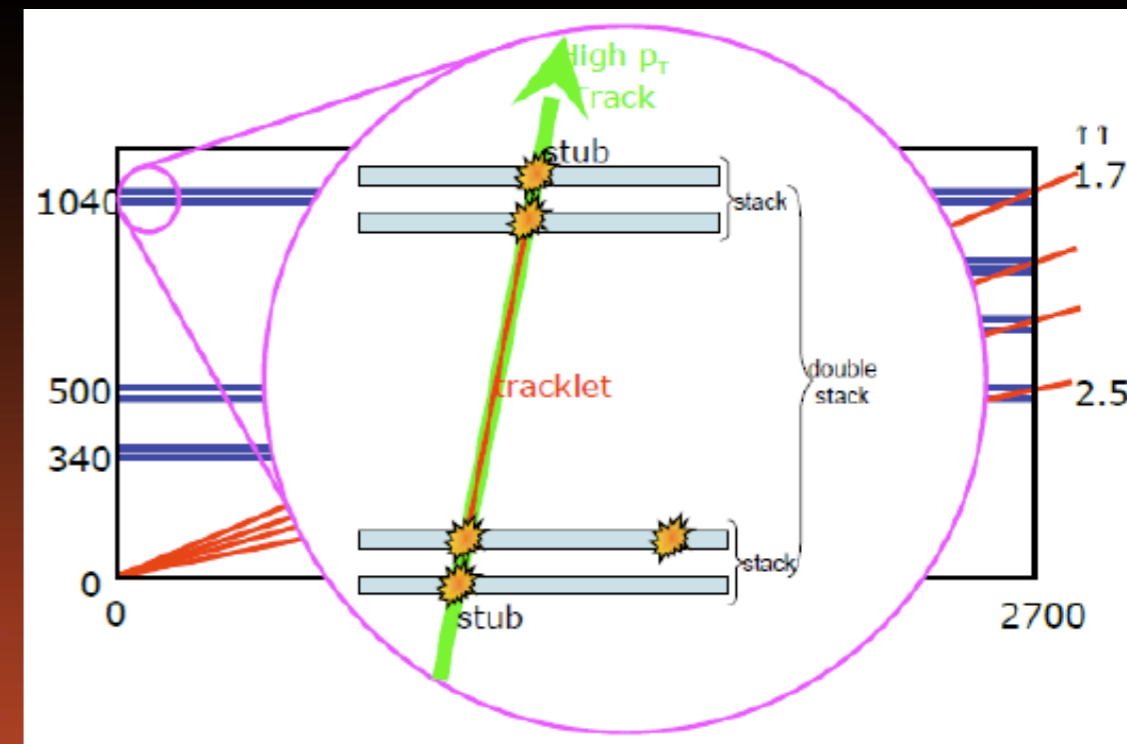


- seed finding in coincidences in 2 adjacent modules

- ➔ double module layers would drive the layout of the upgrade tracker

- track finding/fitting

- ➔ currently investigating FPGA solution
- ➔ consider associative memory (like FTK)



Let's Summarize...

- discussed expected pileup tracking performance
 - ➔ effects on resolutions and fake rates
 - ➔ vertexing and b-tagging
 - ➔ tracking settings to optimize performance and resource needs
- discussed Phase-0 and Phase-1 upgrades
 - ➔ ATLAS and CMS Pixel upgrades
 - ➔ hardware track trigger concepts for Level-1 and Level-2



THAT'S ALL !!!

