

### Outline of this Seminar

- short introduction
- expected tracking performance
- commissioning of Inner Detector reconstruction
  - ⇒ calibration, tracking, alignment, material, ...
- tracking performance
  - → especially in jets and with pileup
  - → vertexing and b-tagging
- upgrade: expected performance improvements with the Insertable B-Layer (IBL)



### Introduction

- broad physics program covered by ATLAS
  - → general purpose pp experiment to cover:
    - SM QCD/W/Z/top, Higgs, SUSY, Exotics, ...
    - some aspects in b-physics
    - ability to do heavy ion physics
- detector designed to optimize physics performance
  - ⇒ at design luminosities (10<sup>34</sup> cm<sup>-2</sup>s<sup>-1</sup>) and pileup (~23 min.bias events)
  - → possibly sustain heavy ion "central" event multiplicities
- task of event reconstruction is to identify objects
  - $\Rightarrow$  e/ $\mu$ / $\tau$  leptons, photons, (b) jets, missing E<sub>T</sub>, exclusive hadronic states...
  - → requires combining information from tracking detector with calorimetric and muon spectrometer measurements
  - → tracking is a central aspect of the event reconstruction



### Introduction

### requirements on ATLAS Inner Detector

- precision tracking at LHC luminosities (central heavy ion event multiplicities) with a hermitic detector covering 5 units in η
- → precise primary/secondary vertex reconstruction and to provide excellent b-tagging in jets
- → reconstruction of electrons (and converted photons)
- → tracking of muons combined with muon spectrometer, good resolution over the full accessible momentum range
- ⇒ enable (hadronic) tau, exclusive b- and c-hadron reconstruction
- **→** provide **particle identification** 
  - transition radiation in ATLAS TRT for electron identification
  - as well dE/dx in Pixels or TRT
- → not to forget: enable fast tracking for (high level) trigger

### constraints on detector design

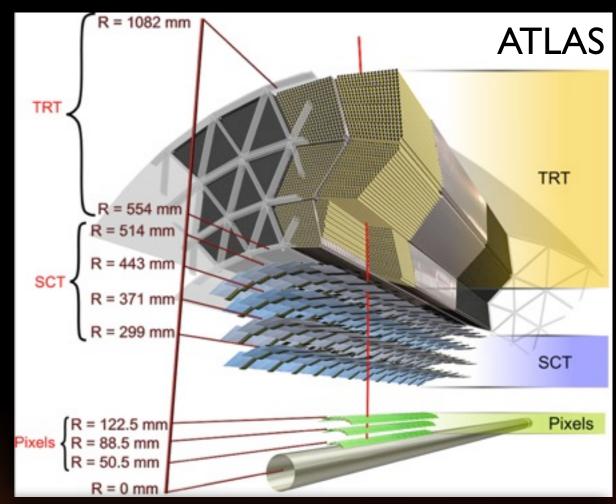
- minimize material for best precision and to minimize interactions before the calorimeter
- ⇒ increasing sensor granularity to reduce occupancy
  - increase number of electronics channels and heat load
  - leading to more material



### ATLAS Inner Detector Layout

### • 3 subsystems:

- → 3 layer Pixel system, 3 endcap disks
  - 1744 Pixel modules
  - 80.4 million channels
  - pitch 50  $\mu$ m  $\times$  400  $\mu$ m
  - total of 1.8 m<sup>2</sup>
- → 4 layers of small angle stereo strips,9 endcap disks each side (SCT)
  - 4088 double sided modules
  - 6.3 million channels
  - pitch 80 μm, 40 mrad stereo angle
  - total of 60 m<sup>2</sup>
- → Transition Radiation Tracker (TRT)
  - typically 36 hits per track
  - transition radiation to identify electrons
  - total of 350K channels

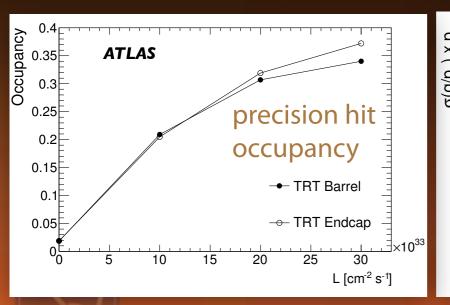


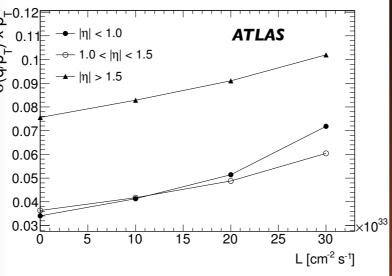


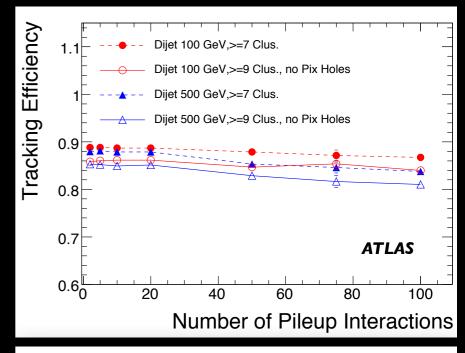


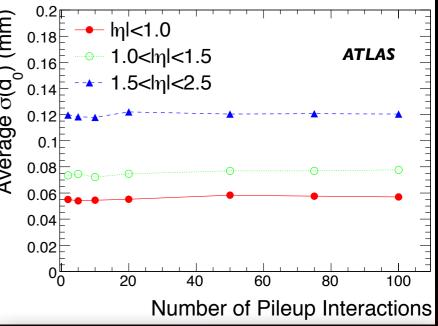
### **Expected Performance**

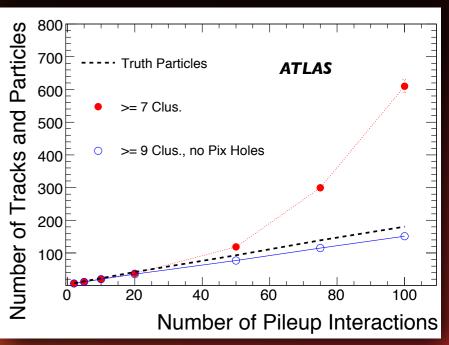
- excellent preparation before startup
  - → more than 10 years of simulation and test beam
  - → cosmics data taking in 2008 and 2009
  - → payed off last year!
- detailed simulation studies
  - → document expected performance in TDRs
  - → few of the known critical items:
    - material effects limit efficiency and resolution at low pt
    - good (local) alignment for b-tagging
    - momentum scale and alignment "weak modes"
  - → focus for commissioning of tracking and vertexing







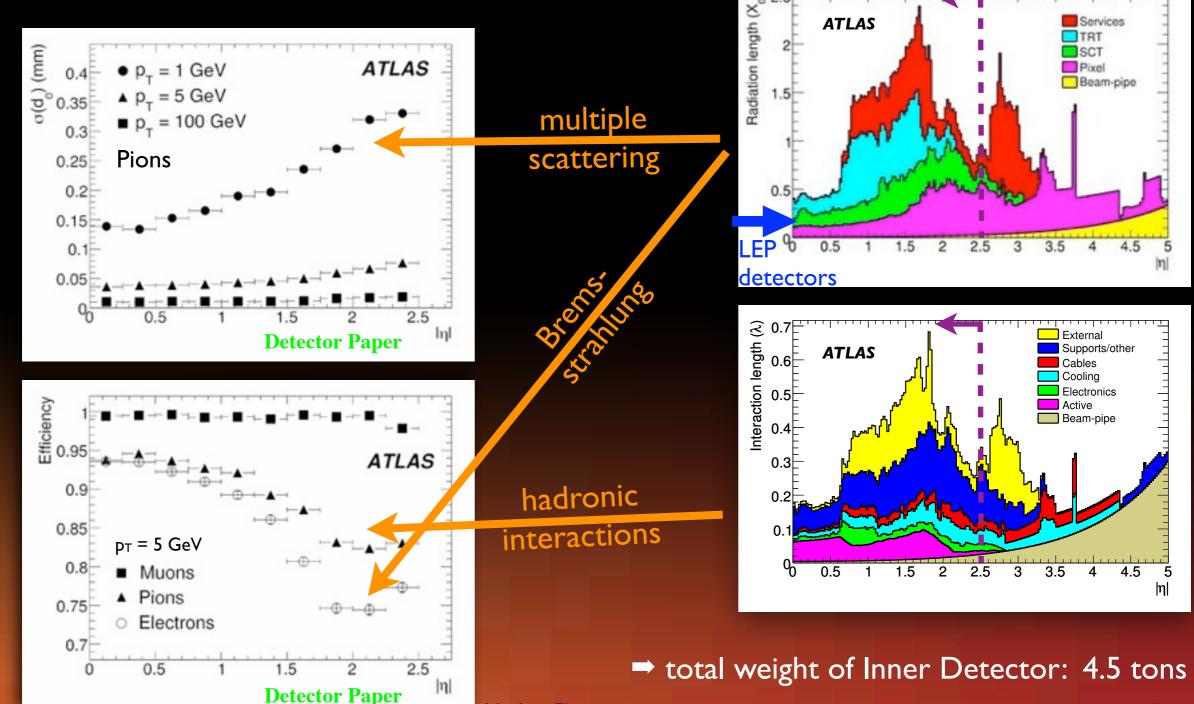




# Material Budget limits Performance!

tracking resolution and efficiency mostly driven by

interactions in detector material





# Weighing Detectors during Construction

### huge effort in experiments

- → put each individual detector part on balance and compare with model
- measured weight of their tracker and its components
- → correct the geometry implementation in simulation and reconstruction

ATLAS	estimated from measurements	simulation
Pixel package	201 kg	197 kg
SCT detector	672 ±15 kg	672 kg
TRT detector	2961 ±14 kg	2962 kg



example: ATLAS TRT measured before and after insertion of the SCT

#### notice:

→ significant increase in material budget since Technical Proposal (we see a similar trend with IBL now)

	ATLAS		CMS	
Date	$\etapprox 0$	$\etapprox1.7$	$\etapprox 0$	$\eta pprox 1.7$
1994 (Technical Proposals)	0.20	0.70	0.15	0.60
1997 (Technical Design Reports)	0.25	1.50	0.25	0.85
2006 (End of construction)	0.35	1.35	0.35	1.50



# Required new Software Technologies

- complex G4 geometries not optimal for reconstruction
  - → simplified tracking geometries
- reduced number of volumes
  - → blending details of material

	G4	tracking
ATLAS	4.8 M	10.2K *

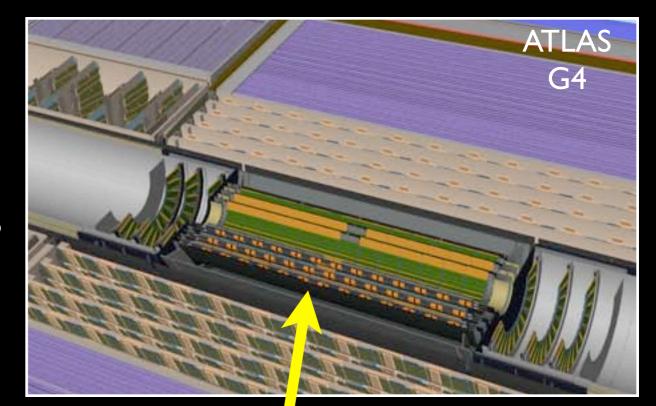
<sup>\*2</sup> plus a surface per Si sensor

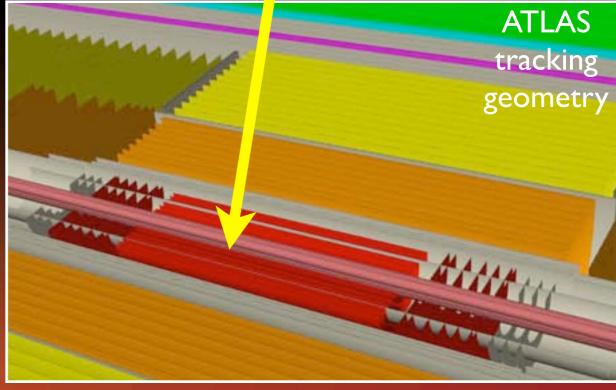
→ use embedded navigation scheme to optimize CPU performance

ATLAS	G4	tracking	ratio
crossed volumes in tracker	474	95	5
time in SI2K sec	19.1	2.3	8.4

(neutral geantinos, no field lookups

→ as well basis of fast simulation engine

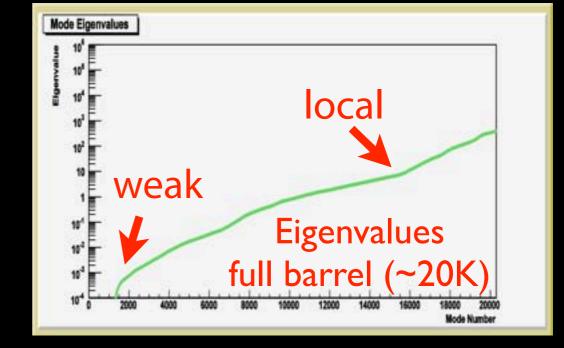


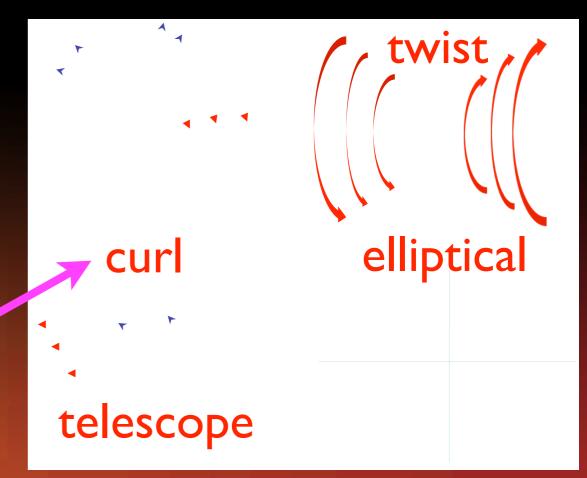




# Alignment and Weak Modes

- global- $\chi^2$  alignment
  - → diagonalize alignment matrix (6 x 6k)<sup>2</sup>
  - → enables studies of Eigenvalue spectrum
    - well constraint : local movements
    - less well constraint : overall deformations
    - not constraint : global transform
- residuals relevant for b-tagging
  - → mostly sensitive to local movements track
  - → well constraint by module overlaps and beam spot constraint





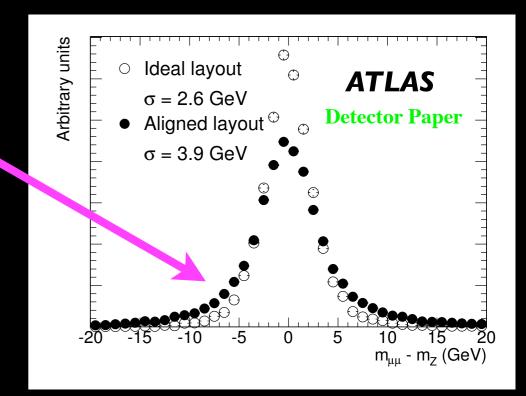


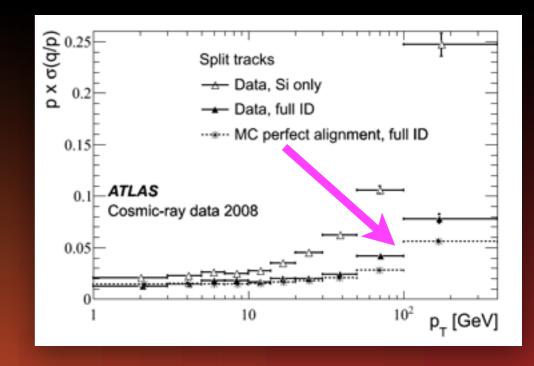
weak modes affect p<sub>T</sub>-scale

 $\rightarrow$  overall deformations that leave  $\Delta \chi^2 \sim 0$ 

# Did we expect Weak Mode Effects?

- "Detector Paper" MC study:
  - → ideal Z mass resolution 2.6 GeV
  - $\rightarrow$  misalign MC by 100  $\mu$ m, re-align using:
    - high-p<sub>T</sub> muons and cosmics
  - → Z mass resolution degraded to 3.9 GeV (!)
    - not corrected by alignment procedure
- cosmics study using split tracks
  - → good performance overall
    - cosmics are mostly in the barrel (!)
    - done with the alignment at the time...
  - → but: at higher p<sub>T</sub> the data starts to diverge from MC
    - reflects limited calibration at the time
    - possible hint for weak mode effect in alignment





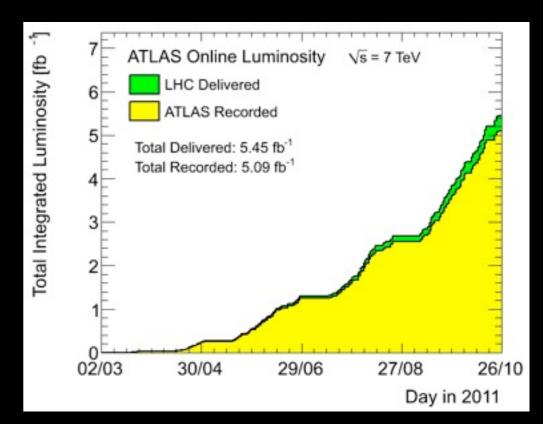


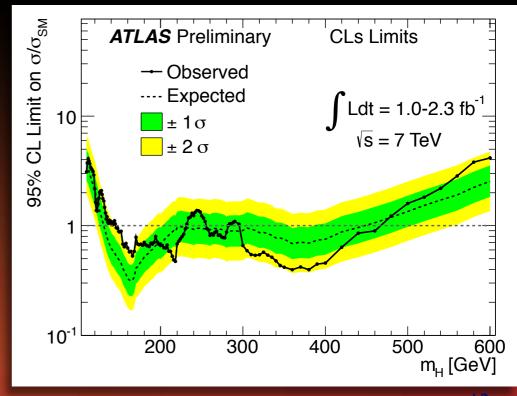
### **Excitement with first beams...**



# Commissioning with Collision Data

- LHC has done fantastic since!
- a long way from first collisions to physics
  - commission full readout chain (detector, trigger, DAQ)
  - → calibrate and align the detector
  - optimize the tracking performance, allow for changing levels of pileup
  - **→** ...
- basis of commissioning the tracking is work done on the detector!
  - → not be able here to do justice to all aspects of detector calibration...





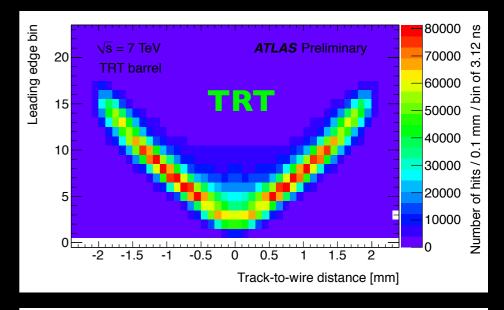


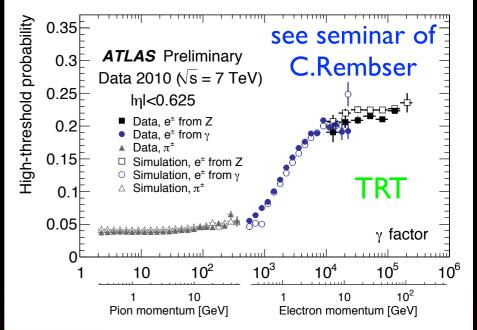
### **Detector Calibration**

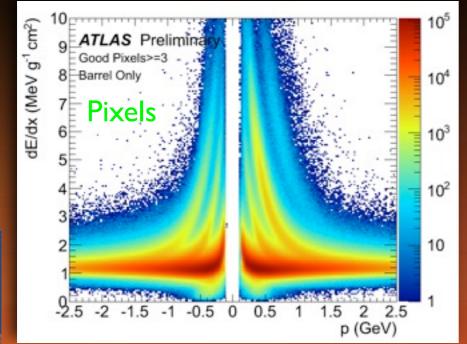
- careful calibration of detectors
  - → required to reach design performance
  - → online (thresholds,...) and offline
  - → monitoring of variations with time

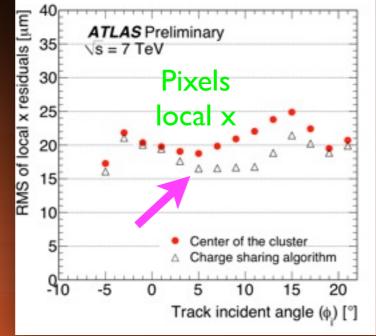
### examples:

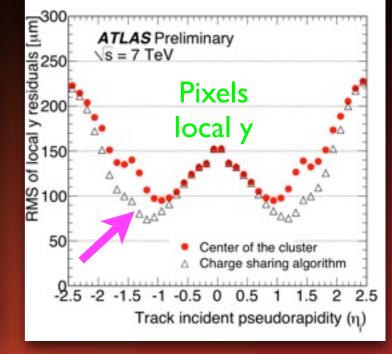
- → TRT: R—t relation and high threshold probability
- → calibration of time over threshold in Pixels
  - required to explore power of analog clustering
  - provide dE/dx for low p<sub>T</sub> particles as well







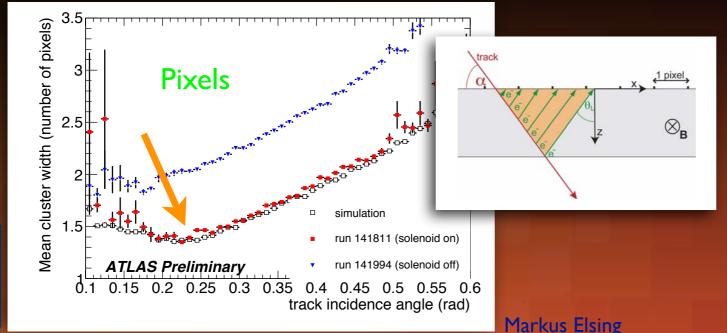


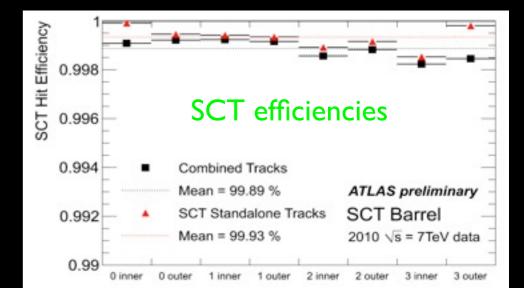


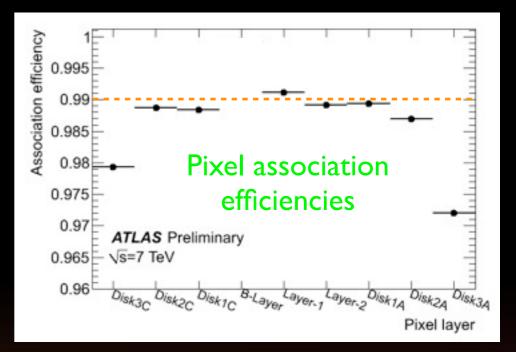


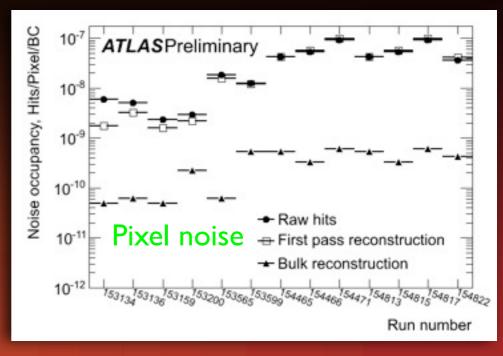
### **Detector Calibration**

- study detector efficiencies
  - → identify dead channels, chips, modules
    - typically ≥97% of detectors are operational
    - after correction for known defects typical sensor efficiencies are >99% (!)
  - → very low noise levels observed in Pixels/SCT
- measure Lorentz angle
  - → as usual study cluster sizes vs track incident angle
  - → input to tuning of cluster properties
    - adjusting digitization parameters to match data





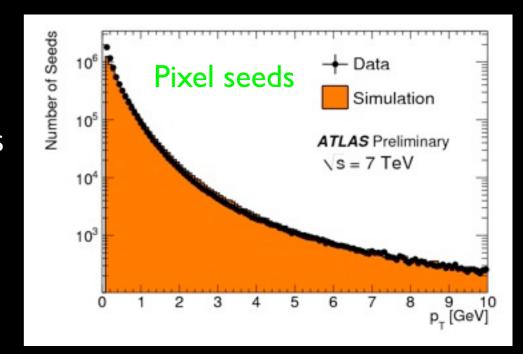


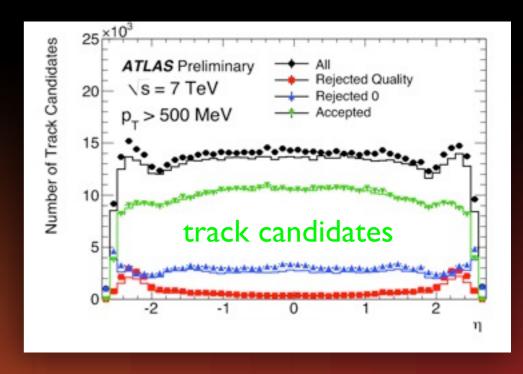




### Pattern Recognition

- 2 staged track reconstruction
  - ⇒ inside-out: Pixel seeded + extending outwards
  - → outside-in: seeded on TRT segments
- ensure "robustness"
  - → allow for dead/noise modules
  - → error scaling to reflect calibration + alignment
  - → especially important at startup
    - very good performance even with early data
- study performance at different levels in reconstruction process
  - ⇒ seeding / candidate fitting / ambiguity
  - ⇒ basis for understanding tracking results

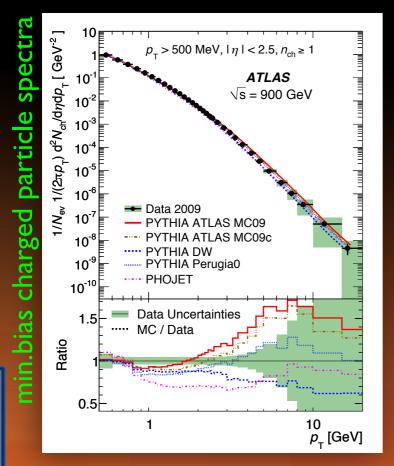


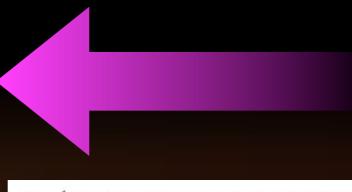


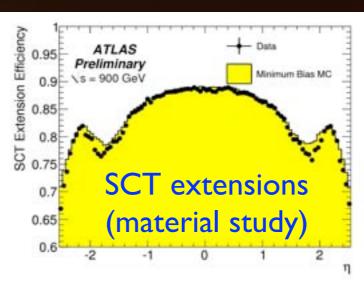


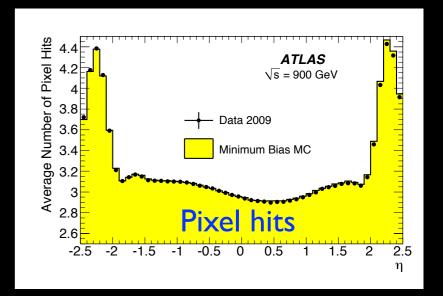
# Tracking Commissioning

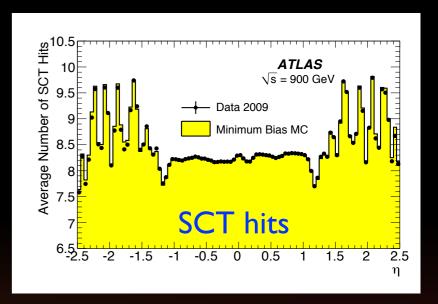
- detailed studies of properties of tracks in 900 GeV data
  - → hit associations, fit quality, etc.
    - allow for known defects in simulation
  - → leading towards first publications
    - as expected, tracking systematics driven by material uncertainties (!!)

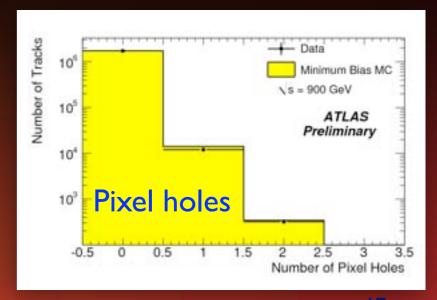














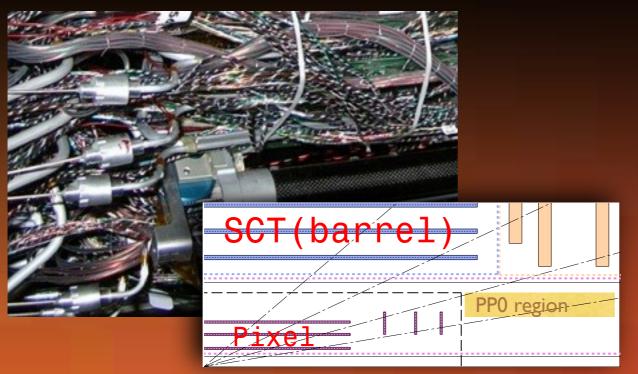
Markus Elsing

1

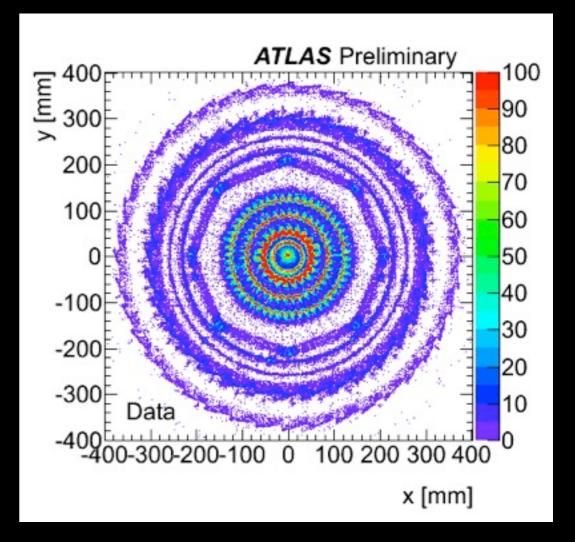
### Conversions

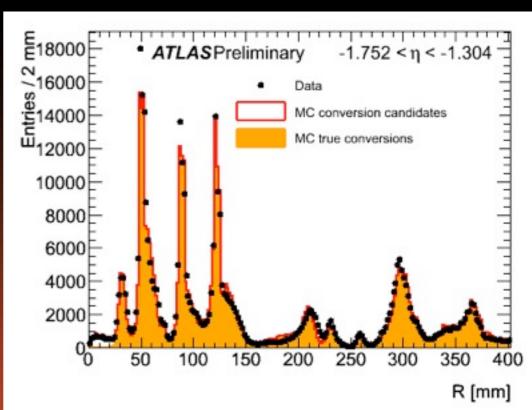
- detailed tomography of material with γ conversions
  - → able to map details in material distribution
    - measure difference in data/MC, e.g. PP0
  - → ultimately should result in a very precise estimate of material
    - need to control reconstruction efficiency
    - calibrate measurement,
       e.g. on "known" beam pipe
    - needs a large dataset to reach precision

ATLAS
Pixel
PP0
region



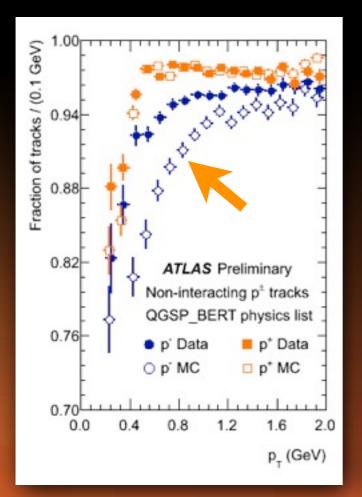


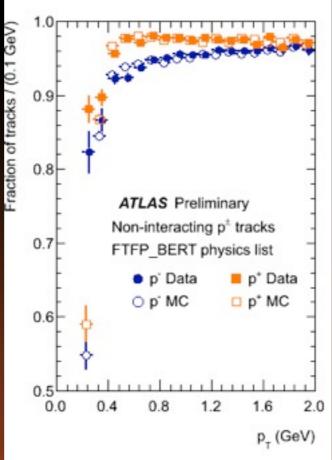


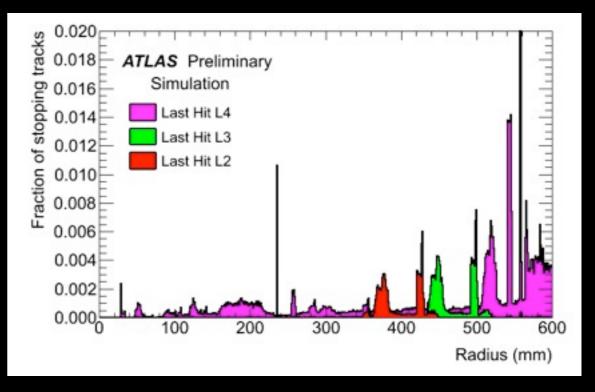


# Stopping Tracks in SCT

- based of last hits on tracks
  - $\rightarrow$  soft p and  $\pi$  from  $K^{0}_{s}$  and  $\Lambda$  decays
  - ⇒ sensitive to material at larger radii
- charge dependences seen
  - → geometry effect (module tilts)
  - → differences in cross sections





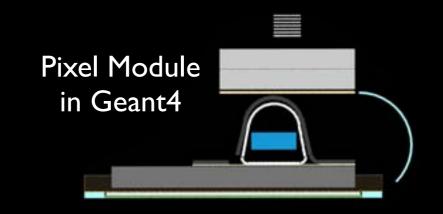


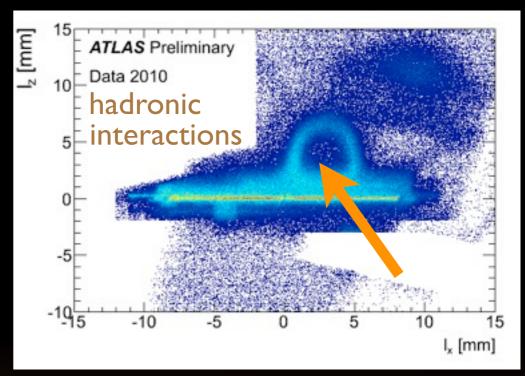
- allows to study modeling of hadronic interactions in G4
  - → QGSP\_BERT does not model anti-protons well
  - ⇒ better described by FTFP\_BERT

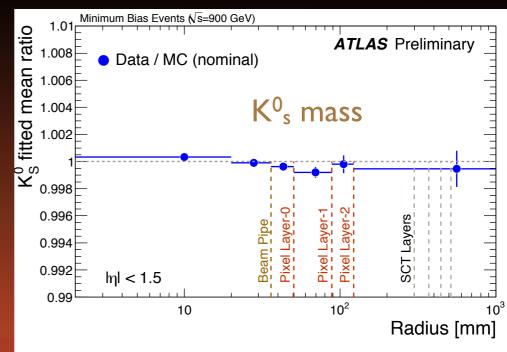


### **Further Material Studies**

- hadronic interactions for precise tomography of detector material
  - ⇒ good vtx resolution allows to study fine details
  - → e.g., study levels of cooling liquid or shift in beam pipe position w.r.t. Pixel b-layer
- material uncertainty in simulation
  - → constraint by sum of different techniques
    - conversions and hadronic interactions
    - study K<sup>0</sup><sub>s</sub> and other mass signals
    - stopping tracks, SCT extension efficiency
    - study of multiple scattering resolution term
  - → estimated uncertainty
    - better than ~5% in central region
    - at the level of ~10% in most of the endcaps





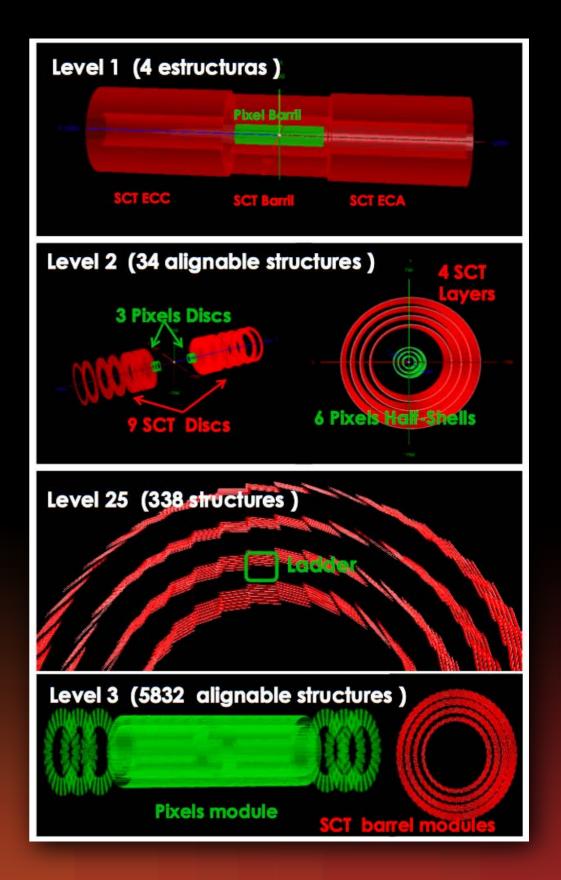




### Detector Alignment

- alignment strategy
  - → starting point is detailed survey
  - ⇒ alignment stream with high-p<sub>t</sub> tracks
    - mix pp and cosmic data
  - → define different levels of granularity
    - level 1 (e.g.SCT barrel)
    - level 3 (module)
  - $\rightarrow$  global- $\chi^2$  and local alignment

Structures	Pixel	SCT	TRT
Levell	l l	3	3
Level 2	12	22	96
Level 3	1744	4088	350848





### Detector Alignment

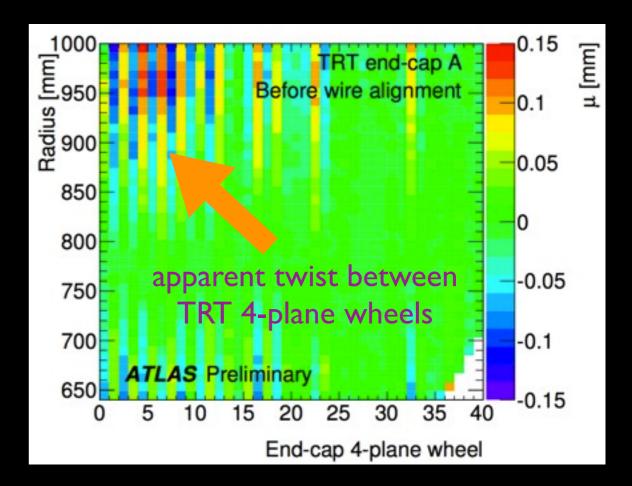
- is an art...
  - → plenty of subtle effects to allow for
- Pixel stave bowing
  - probably mechanical stress from mounting

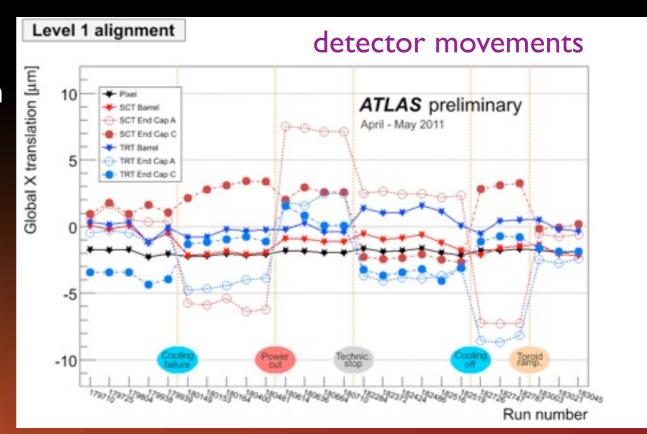


- → twist between 4 plane wheels
- → traced back to the wheel production
- → fix with alignment of each wire (!!)

### detector movements

- → traced back to
  - cooling failures
  - power cuts
  - magnet ramps
- ⇒ level-1 movements of  $\sim 5\mu m$  (mostly)



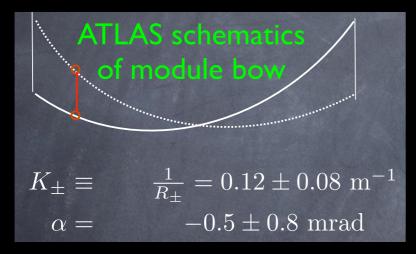


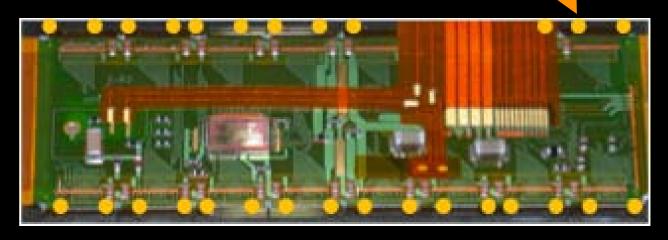


### Pixel Modulagoistorpioms

survey points

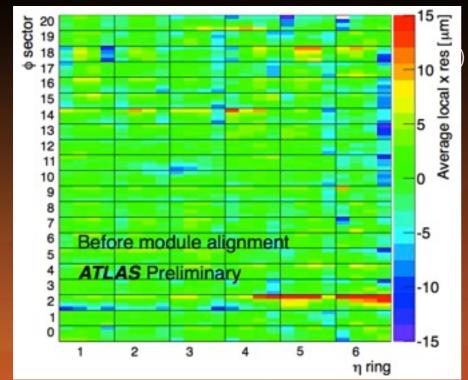
survey told us Pixel modules are not flat

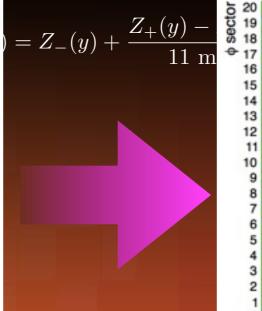


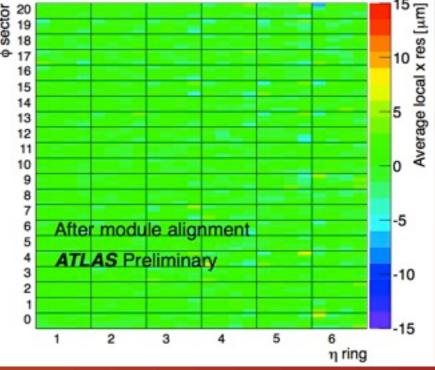


correct cluster positions for module shape

 $\Rightarrow$  significant improvement in  $e^{i n + e} = s \log (1 + e) \log (1 +$ 



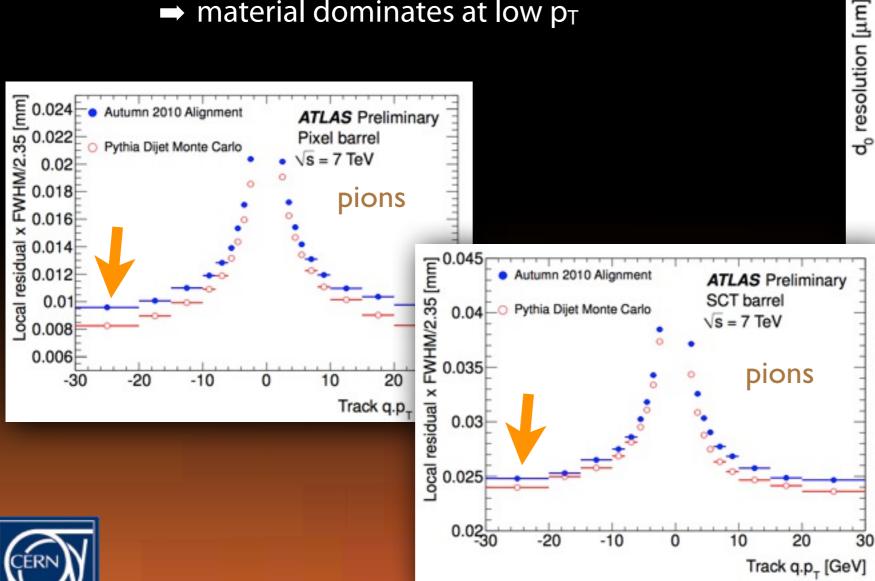


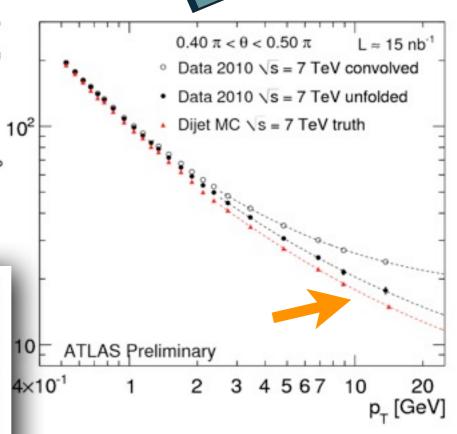




# Residuals and Impact Resolution

- driven by local misalignments
  - → quickly approaching design resolutions
  - → some small problems still visible
    - hence apply some error scaling in fit
  - → material dominates at low p<sub>T</sub>

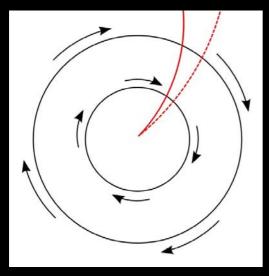




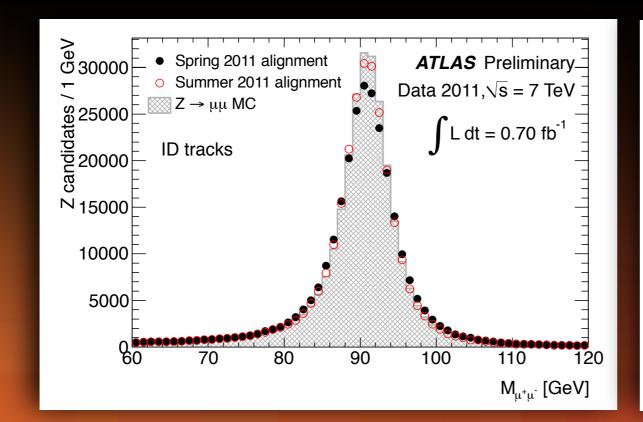


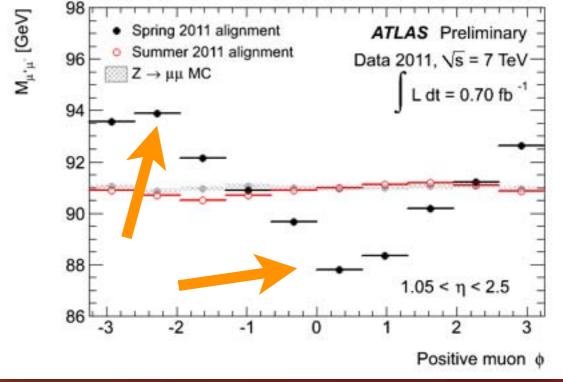
### Evidence for Weak Modes?

example: curl weak mode



- "weak modes" are global deformations
  - $\rightarrow$  leave fit- $\chi^2$  nearly unchanged
  - → affect momentum scale, e.g. Z-mass resolution
- limiting performance in data
  - $\rightarrow$  saw modulation in Z mass vs  $\phi(\mu^+)$  in endcaps
- external constraints to control weak modes
  - → TRT to constrain Silicon alignment
  - ⇒ currently: electron E/p using calorimeter
  - → check: muon momentum in tracker vs muon spectrometer

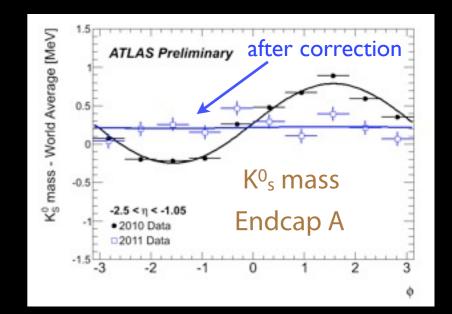


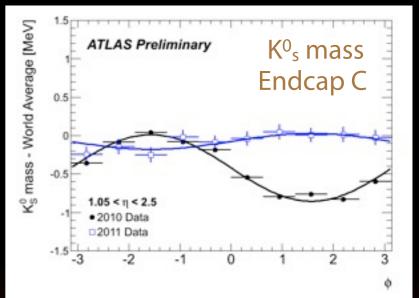


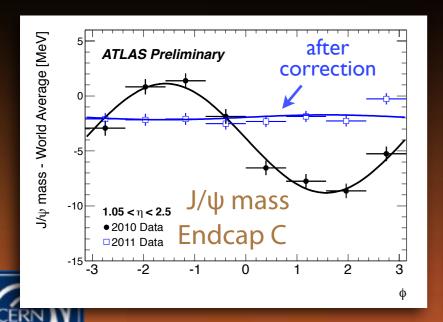


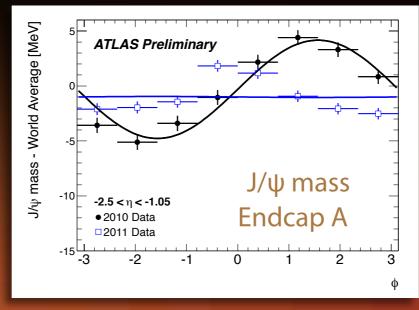
### Detector tilt vs B-Field

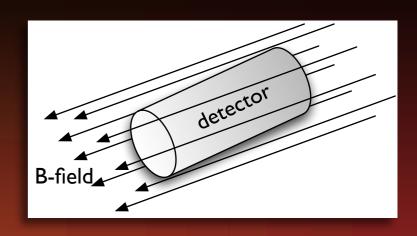
- tilt in visible in  $K^0_s$  and  $J/\psi$  mass bias as a function of  $\varphi$ 
  - → results in a sine modulation in mass in opposite directions in both endcaps
  - ⇒ corrected by **0.55** *mrad* field rotation around y
    - roughly consistent with survey constraints





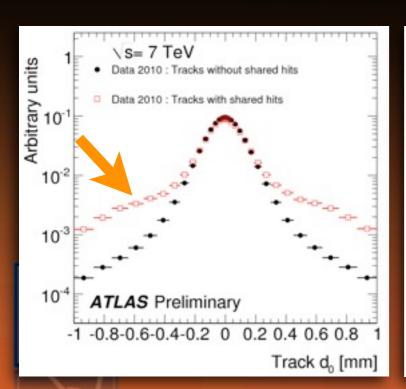


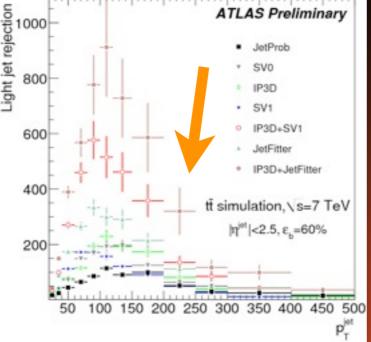


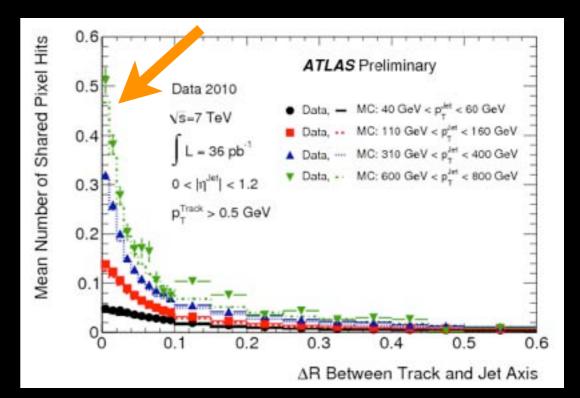


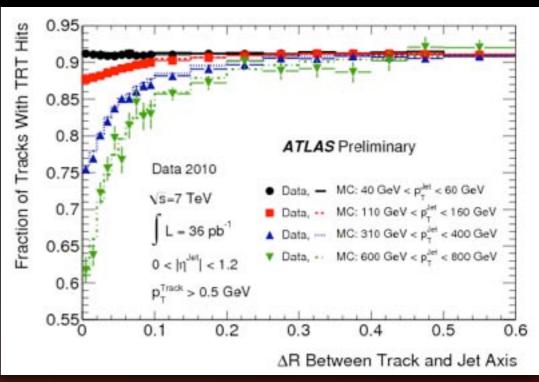
# Tracking in Jets

- double track resolution effects?
  - ⇒ study tracks vs p<sub>T</sub> of anti-k<sub>T</sub> (0.6) jets
- several effects visible in jet core
  - → shared hits in Pixels
  - → TRT association efficiency (quality cuts)
- limits tracking performance
  - → especially for b-tagging!
  - → loss in rejection at high-p<sub>T</sub>





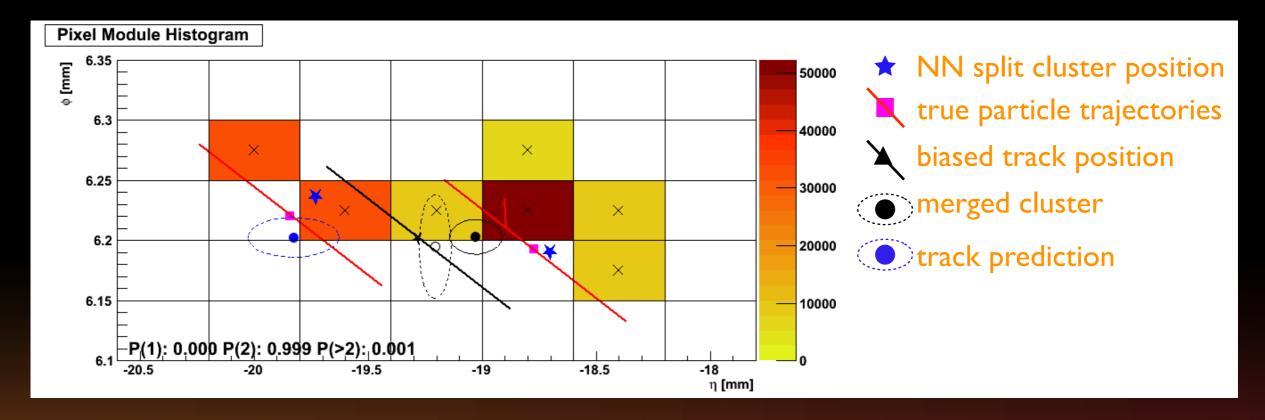




- new clustering to improve
  - explore full analog information in Pixels

### Merged Pixel Clusters

- typical merged cluster with naive clustering algorithm
  - → old clustering was searching for all neighboring pixels that fired
  - ⇒ analog information just used to estimate barycenter of cluster

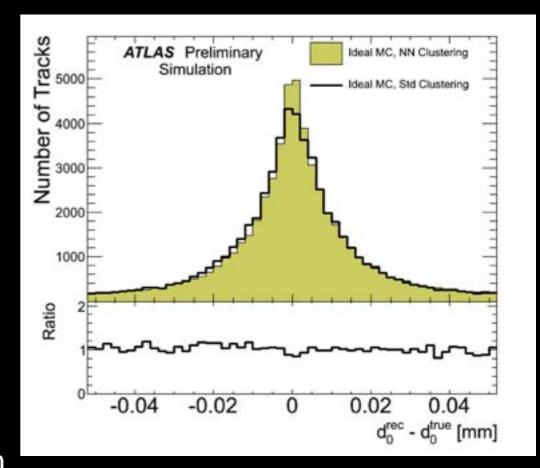


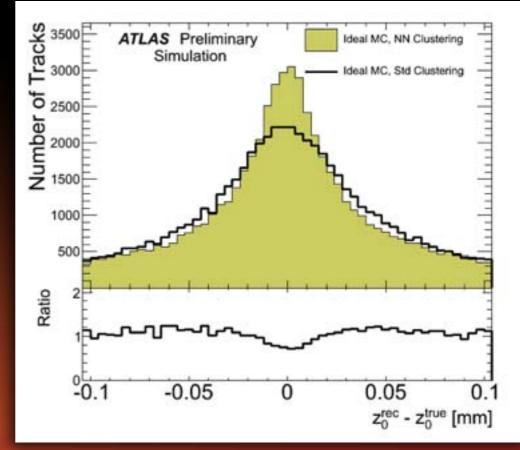
- many merged clusters can be resolved using full analog information
  - → process pre-clusters Pixel information to split them if possible



### New Pixel Clustering

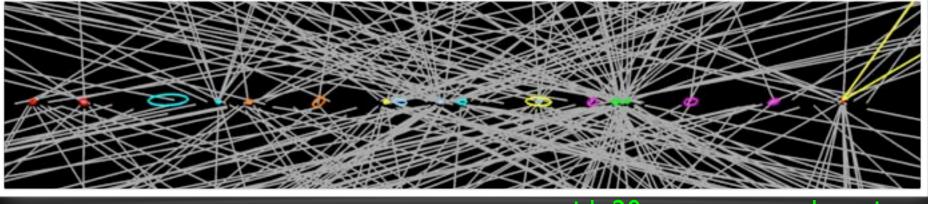
- novel algorithm to split merge clusters
  - → neural network (NN) based technique
  - → run 5 networks:
    - NN1: probability a cluster is 1/2/>2 tracks
    - NN2: best position for each (sub)cluster
    - NN3: error estimate for cluster
    - NN4+5: redo NN2+3 using track prediction
  - → adapt pattern recognition
- new clustering been deployed in recent 2011 reprocessing
  - ⇒ improved cluster resolution, especially in z
  - → dramatic reduction in rate of shared b-layer hits due to unresolved merged clusters





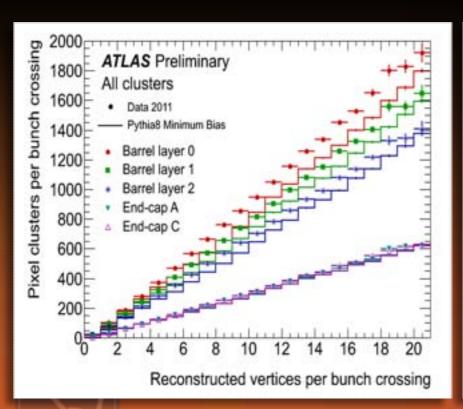


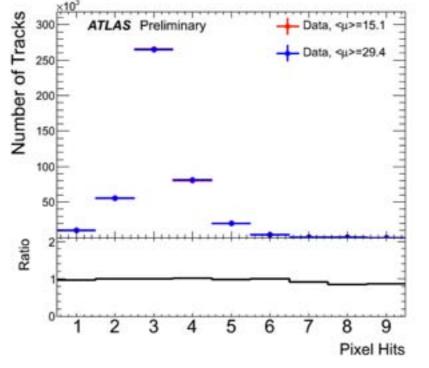
### Pileup

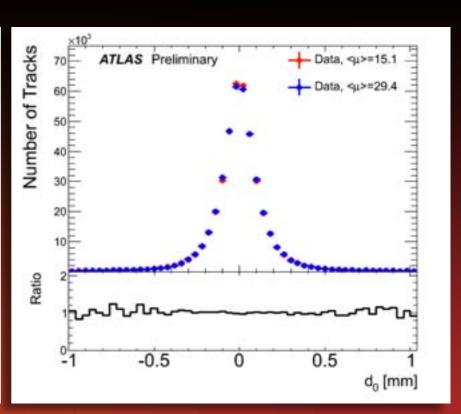


event with 20 reconstructed vertices

- event pileup is a reality
  - ⇒ in 2011 we reached 50% of design levels, but at 50 nsec bunch spacing
  - → may expect 2-3 times increase in 2012
- occupancies and tracking performance as expected
  - → recent high pileup LHC runs very useful to study high pileup regime
  - → resolutions and reconstruction efficiencies are not affected
  - → fake rate is naturally increasing with loose tracking cuts





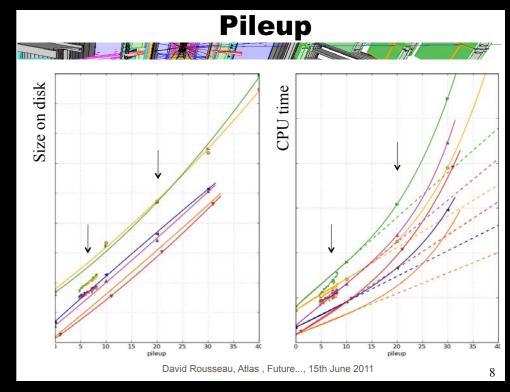


### Pileup and Resources

- resource needs scale fast
  - → tracking is a resource driver
- global optimization
  - → requirements on tracking evolves with physics program
  - → different luminosity regimes lead to different working points

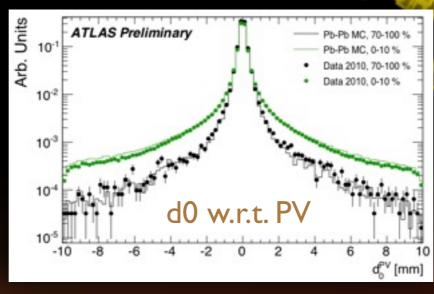
2009 / early 2010	commissioning Min.Bias	pt > 50 MeV open cuts, robust settings min. 5 clusters
2010 stable running < ~4 events pileup	low lumi physics program (soft QCD, b-physics,), b-tagging	pt > 100 MeV min. 7 clusters
2011 pp running ~11 events pileup	focus more on high-pt physics (top, W/Z, Higgs), b-tagging	pt > 400 MeV, harder cuts in seeding min. 7 clusters
Phase I upgrade including IBL 24-50 events pileup	high-pt physics, study new physics (I hope), b-tagging	pt > 900 MeV, harder tracking cuts, min. 9 clusters
SLHC up to 100-200 events pileup	replace Inner Detector to cover very high luminosity physics program	further evolve strategy R-o-l or z-vertex seeding, reco. per trigger type, GPUs

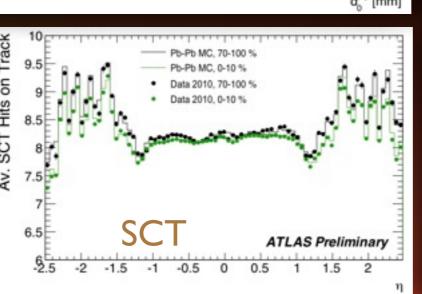


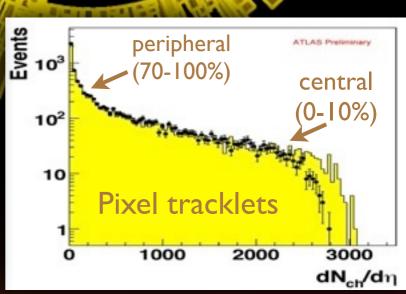


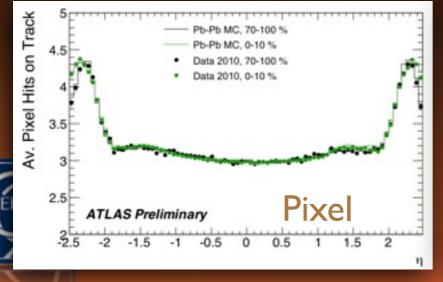
# Heavy Ion Tracking

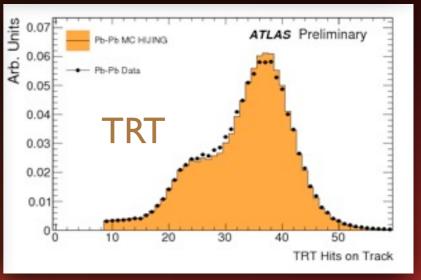
- high multiplicity tracking
  - → adapt seed finding (z vertex constraint to save CPU)
  - → tighten hit requirement to control fakes in central events (similar to sLHC setup)
- excellent tracking performance
  - → even in central events
  - performance well described by MC
  - → good testing ground for high in-time pileup with data







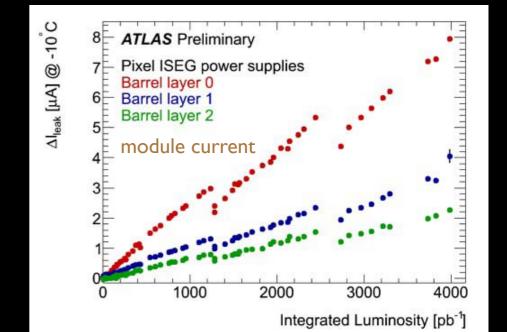


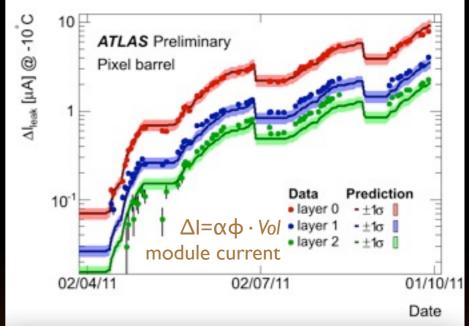


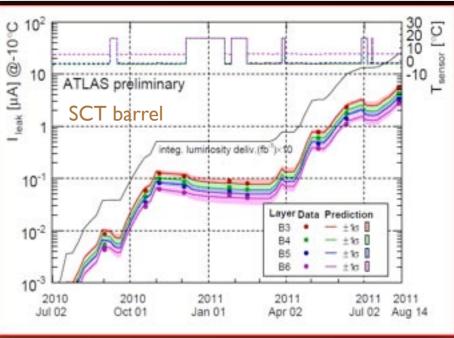
### Radiation Damage

- effects became visible in recent months with increasing luminosity
  - → b-layer:
    - $\phi = 2.43 \cdot 10^{12} \cdot (1 \text{ MeV neq})/\text{fb}^{-1}$
    - type inversion at ~10 fb<sup>-1</sup>
- monitor radiation effects on silicon
  - → leakage current and cross talk measurements
- currents from HV power supplies
  - → compare measured leakage currents with:
    - lumi profile
    - expected fluence from Phojet/Fluka
    - silicon volume
    - damage constant a from test beam
  - good agreement for Pixels and SCT after correction for annealing periods
    - cooling off, e.g. during technical stops



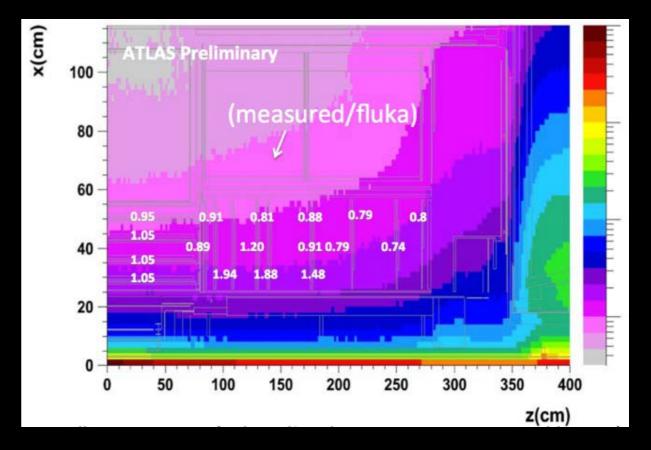






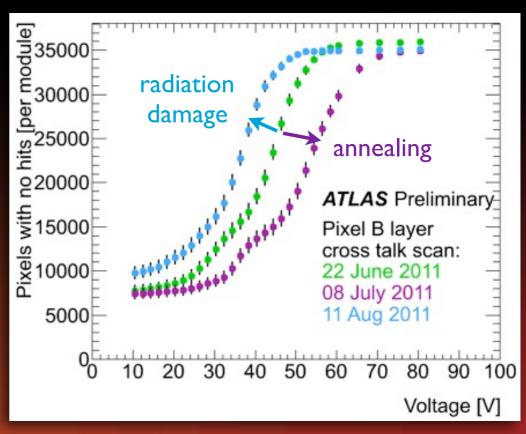
### Radiation Damage

- comparison of measured fluences with Fluka
  - → SCT leakage currents
  - → good agreement in barrel, endcaps show some differences
  - → consistently higher at inner rings (due to different sensors?)



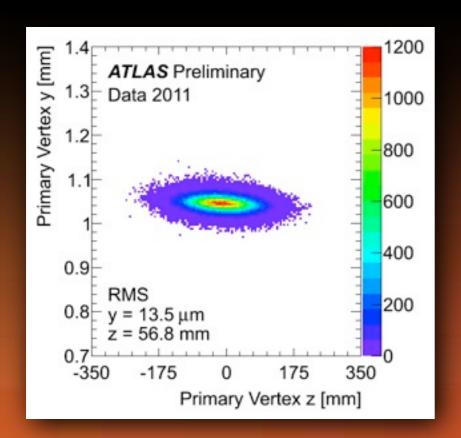
- cross-talk measurements (before type inversion)
  - → inject charge into one pixel, read neighbor:
    - not fully depleted: high-ohmic short
    - ▶ fully depleted: pixels are isolated
  - → annealing effects induced an increase in Vdep from June to July

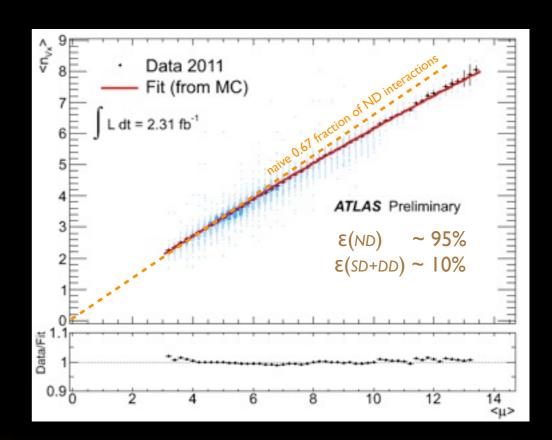


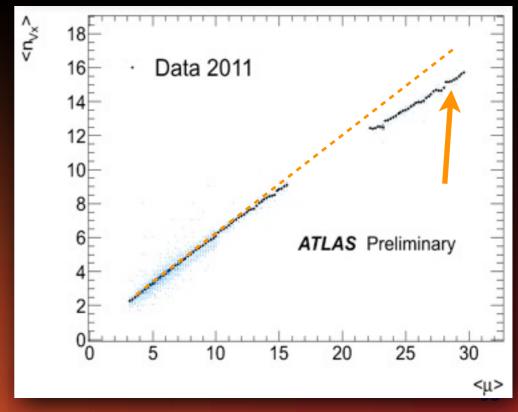


# Primary Vertex Reconstruction

- beam spot routinely determined
  - → averaged over short periods of time (LB)
  - → input to primary vertex reconstruction as a constraint
- primary vertex finding
  - → ATLAS (and CMS) use an iterative vertex finder and an adaptive fitter
  - ⇒ some reduced efficiency for min.bias pileup vertices vs <µ>



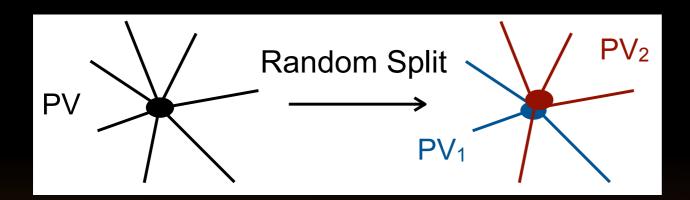




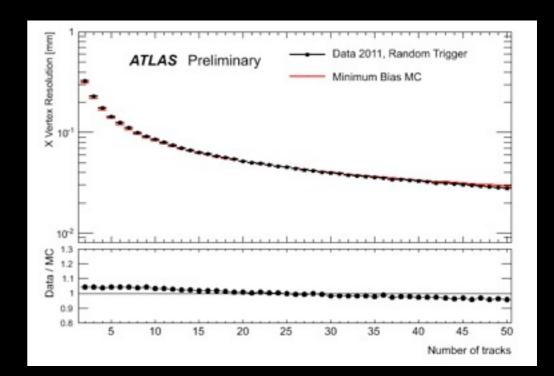


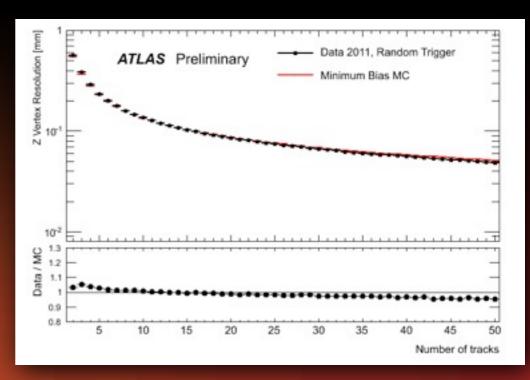
# Primary Vertex Resolution from Data

- primary vertex is input to btagging, etc.
  - need to understand precisely the resolution in data



- split vertex technique
  - → data driven method
  - ⇒ split vertex in 2 and study difference in the2 fitted positions as function of n tracks
  - → very good description in MC

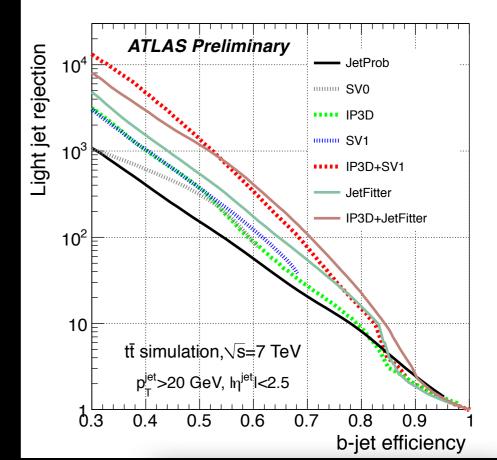


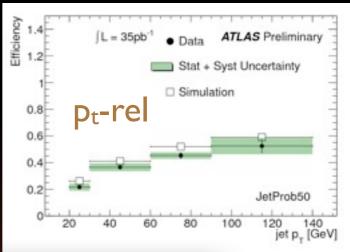


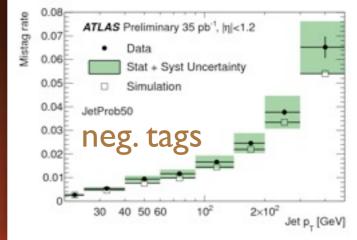


# b-Jet Tagging

- "early tagging" techniques
  - **⇒ soft lepton** tagger
  - **→ track counting** of significant IP offsets
  - **⇒** jet probability
    - construct probability that IP significance of all tracks in jet is compatible with PV
  - **⇒ secondary vertex** (SV) tagger
    - decay length significance
- more elaborate taggers
  - → use multi-variant techniques to classify jets
  - → construct IP based likelihood using b/c/light templates (IP2D and IP3D)
  - → combined likelihood taggers using IP and secondary vertex information (IP3D+SV0)
  - → vertex decay chain tagger (JetFitter)
  - → in regular use since this summer
- data driven performance studies!







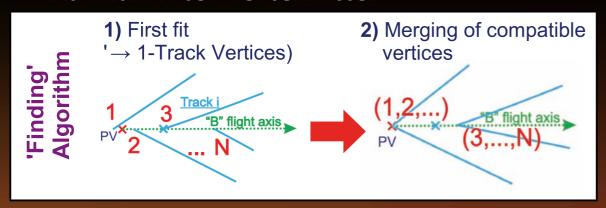


# JetFitter as a b-Jet Tagger

- conventional vertex tagger
  - → fits all displaced tracks into a common geometrical vertex

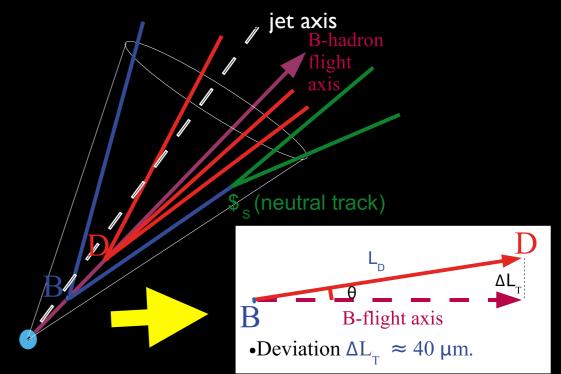
### JetFitter

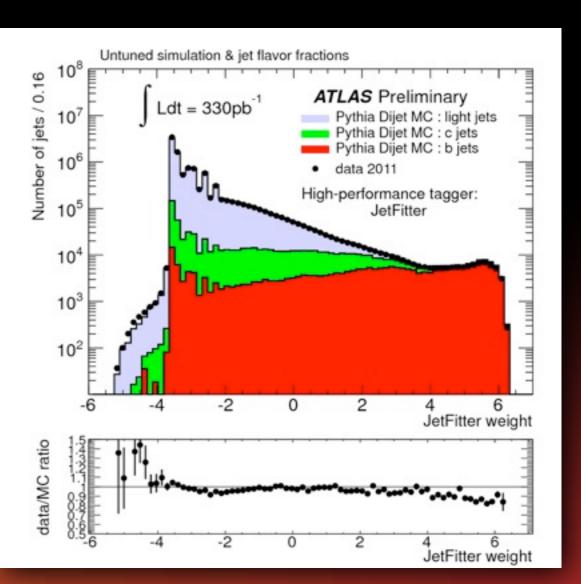
- → b-/c-hadron vertices and primary vertex approximately on the same line
- → fit of 1...N vertices along jet axis
- → mathematical extension of conventional Kalman filter vertex fitter



up to 40% better light rejection

→ IP3D+JetFitter is best b-jet tagger in use in ATLAS today

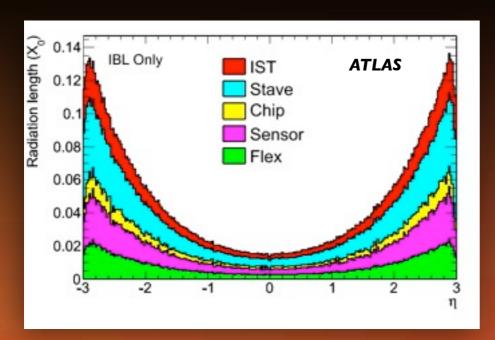


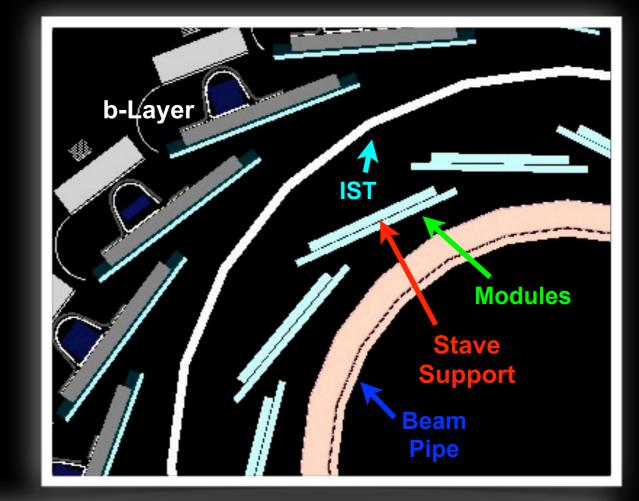


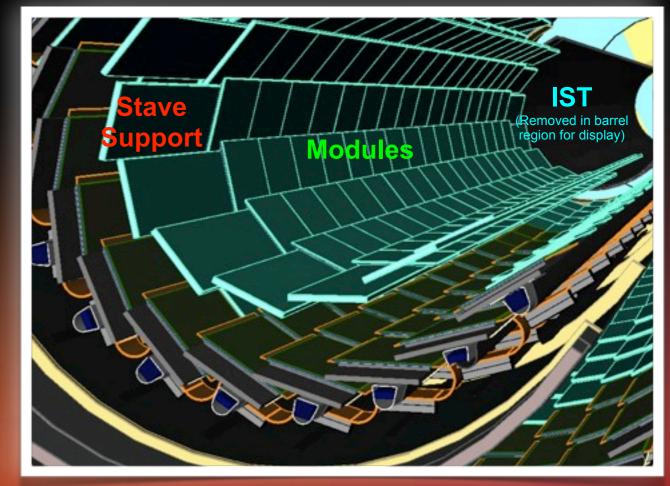


# Outlook: IBL Tracking

- performance studies in G4
  - $\rightarrow$  smaller beam pipe ( $R_{min} = 25 mm$ )
  - → reconstruction: 4th Pixel layer
  - → IBL material adjusted to 1.5% X<sub>0</sub>
  - ⇒ smaller z pitch (250 um)
- installation next shutdown
  - → ready for 14 TeV running
  - → peak luminosities of 2\*10<sup>34</sup> cm<sup>-2</sup>s<sup>-1</sup>
  - → 25-50 pileup events



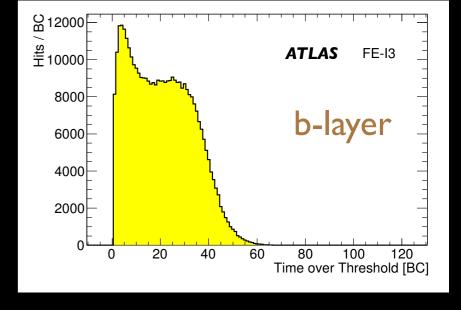


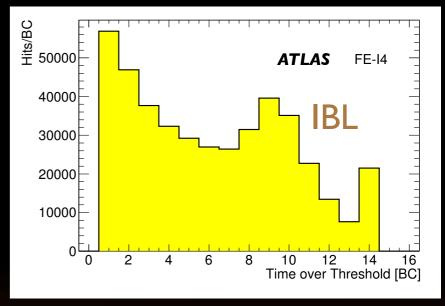


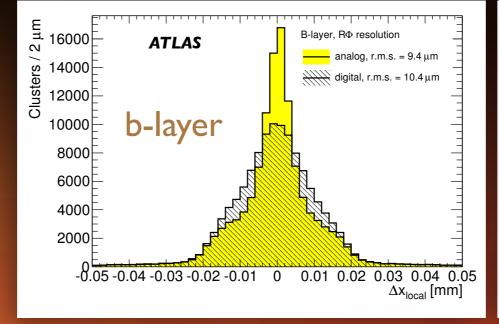


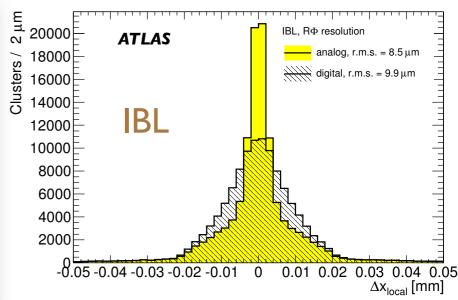
# New FE-14 Chip

- 4bit (FE-I4) calibration vs 8bit (FE-I3)
  - → different dynamic range
    - and FE-I4 allows for overflows
  - → average cluster size in IBL bigger than in b-layer
    - broader spectrum of incident angles
- compare cluster resolutions IBL (FE-I4) and b-layer (FE-I3)
  - $\rightarrow$  similar in  $X_{local}$ , pitch drives improvement in  $Z_{local}$











# Tracking Performance (no Pileup)

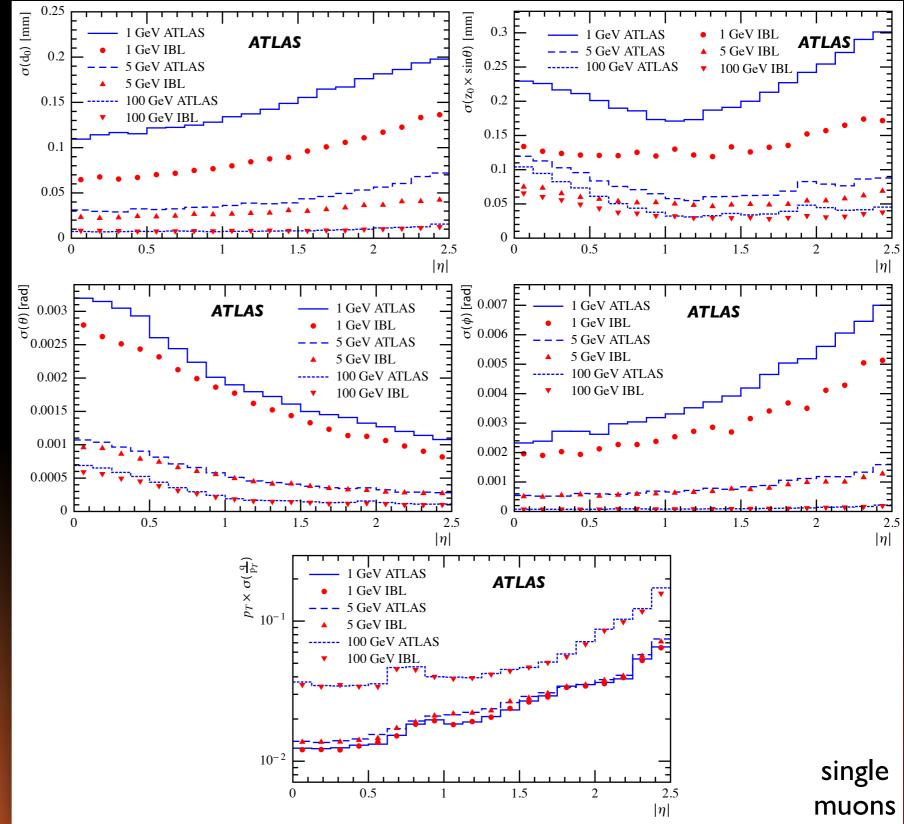
### expected results

- **⇒** smaller radius
- ⇒ small z pitch
- → less material between first and 2nd layer
- → track length ~ same

### improvements

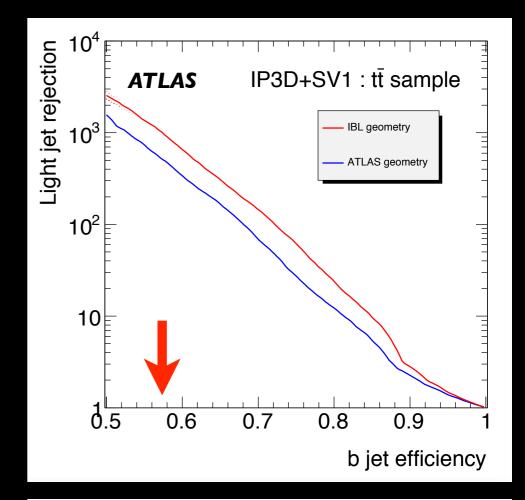
- → better d<sub>0</sub> resolution
- → better z<sub>0</sub> resolution
- θ and φ improved at low-pT
- momentum resolutionunchanged
- as expected!

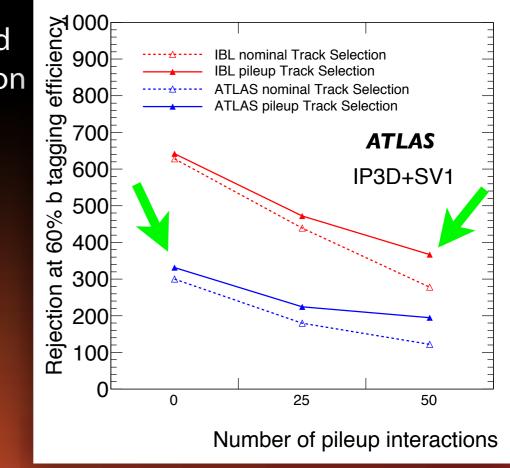




# b-Tagging with IBL

- pileup selection with IBL
  - ⇒ ≥10 IBL+Pixel+SCT hits, ≤1 pixel hole
  - ⇒ benefit from additional layer
  - → leaves room for eventual inefficiencies in b-layer (tracking robustness)
- state of the art b-tagging
  - ⇒ "IP3D"  $\sim d_0 \oplus z_0$  impact significance likelihood
  - → "IP3D+SV1" ~ adding secondary vertex information
- good performance with IBL and pileup
  - → as good or better as for current ATLAS without pileup

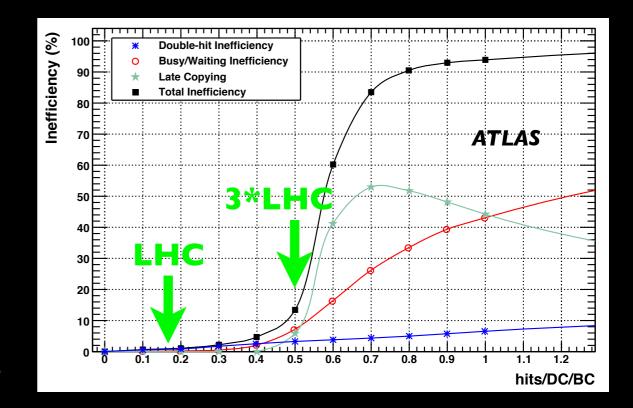


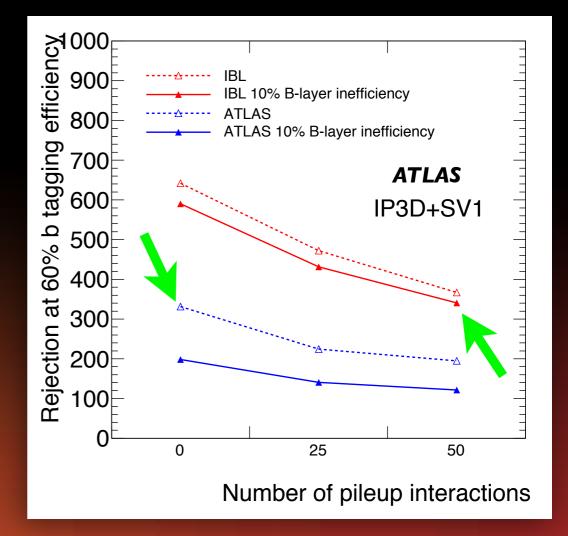




### **Detector Defects?**

- IBL helps to recover from detector defects
  - → known bandwidth limitations of current FE-I3 chip leading to cluster inefficiencies
    - especially in b-layer (r=4cm)
  - ⇒ eventual additional (known) dead modules
- study effect of 10% cluster inefficiency in b-layer with IBL
  - → IBL fully recovers tracking efficiency and impact resolution
  - → with IBL only small effects on b-tagging performance
  - ⇒ similar results for other failure scenarios







### Summary

- stringent requirements on Inner Detector to cover ATLAS physics program
- excellent performance reached!
  - → years of preparation based on simulation and test beam
  - → commissioning with cosmics and early beam
  - → detailed studies of detector, tracking, material, alignment, pileup...
  - → Heavy Ion running gave good insights into tracking at high occupancy
- tracking studies with IBL demonstrate performance of the detector with a 4 layer Pixel system at Phase 1 luminosities

